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NTC	Ted Carnevale
MLH	Michael Hines
WWL	Bill Lytton
FS	Felix Schürmann

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# **CNS\*2007 NEURON Course**

**Toronto, Canada  
Wednesday, July 11, 2007**

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Ted Carnevale  
Bill Lytton  
Felix Schürmann**

**Supported by NINDS**



# The What and the Why of Neural Modeling

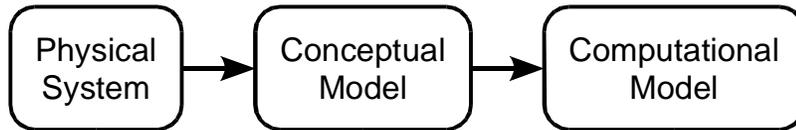
The moment-to-moment processing of information in the nervous system involves the propagation and interaction of electrical and chemical signals that are distributed in space and time.

Empirically-based modeling is needed to test hypotheses about the mechanisms that govern these signals and how nervous system function emerges from the operation of these mechanisms.

## Topics

1. How to create and use models of neurons and networks of neurons
  - How to specify anatomical and biophysical properties
  - How to control, display, and analyze models and simulation results
2. How NEURON works
3. How to add user-defined biophysical mechanisms

## From Physical System to Computational Model



### Conceptual model

a simplified representation of the physical system

### Computational model

an accurate representation of the conceptual model

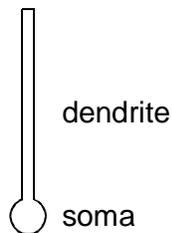
## From Physical System to Computational Model

Physical system



Ca1  
pyramidal  
cell

Conceptual model



ball  
and  
stick

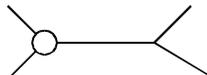
Computational model

```
create soma, dendrite  
connect dendrite(0), soma(1)
```

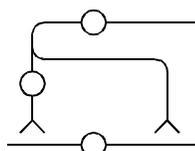
hoc  
code

## Hierarchies of Complexity Structure

Single compartment 

Stylized 

Anatomically detailed 

Network 

## Hierarchies of Complexity Mechanism

Passive and Active currents

HH-style  
kinetic scheme

Synaptic transmission

continuous  
spike-triggered

Gap junctions

Extracellular fields, Linear circuits

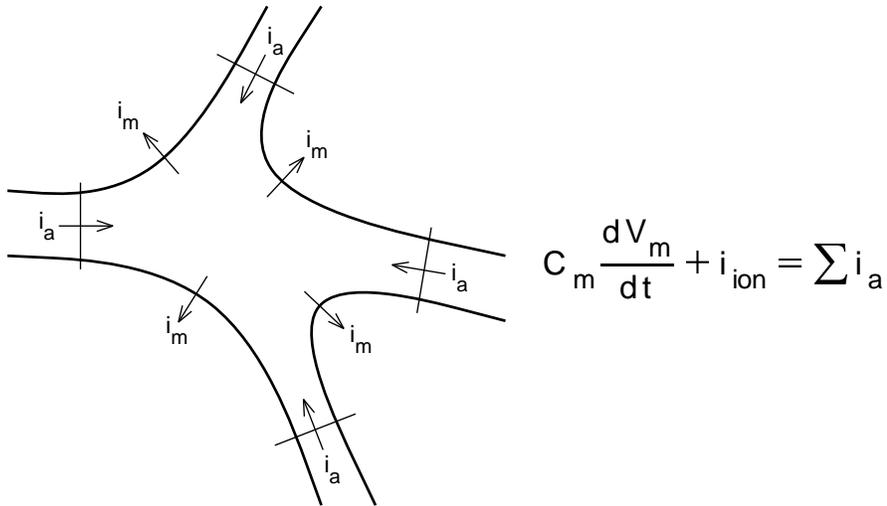
Diffusion, buffers, transport & exchange

Artificial spiking cells ("integrate & fire")

## Fundamental Concepts in NEURON

Signals	Flux	Driving force	What is conserved
Electrical	current	voltage gradient	charge
Chemical	solute	concentration gradient	mass

## Conservation of Charge



## The Model Equations

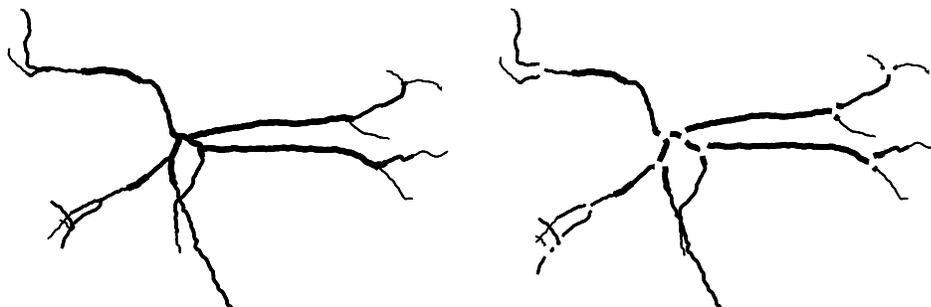
$$c_j \frac{dv_j}{dt} + i_{ion_j} = \sum_k \frac{v_k - v_j}{r_{jk}}$$

- $v_j$  membrane potential in compartment  $j$
- $i_{ion_j}$  net transmembrane ionic current in compartment  $j$
- $c_j$  membrane capacitance of compartment  $j$
- $r_{jk}$  axial resistance between the centers of compartment  $j$  and adjacent compartment  $k$

## Separating Anatomy and Biophysics from Purely Numerical Issues

section

a continuous length of unbranched cable



Anatomical data from A.I. Gulyás

## Range Variables

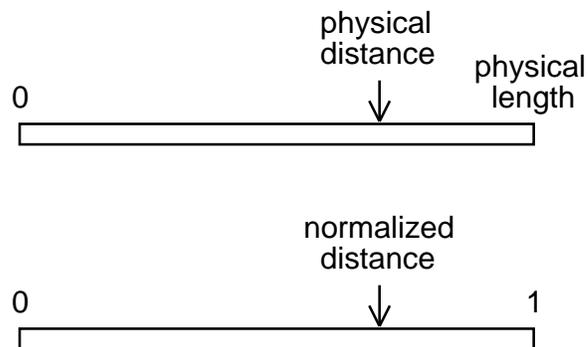
Name	Meaning	Units
diam	diameter	[ $\mu\text{m}$ ]
cm	specific membrane capacitance	[ $\mu\text{f}/\text{cm}^2$ ]
g_pas	specific conductance of the pas mechanism	[siemens/ $\text{cm}^2$ ]
v	membrane potential	[mV]

### range

normalized position along the length of a section

$$0 \leq \text{range} \leq 1$$

any variable name can be used for range, e.g. x



**Syntax:**

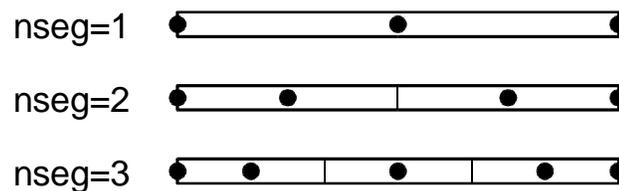
```
sectionname.rangevar(range)
  returns or sets the value of rangevar
  at the location corresponding to range
```

**Examples:**

```
dend.v(0.5)
  returns membrane potential at the middle of dend
  Shortcut: dend.v
dend for (x) print x*L, v(x)
  prints physical distance and v
  at each point in dend where v was calculated
```

**nseg**

the number of points in a section section where membrane current and potential are computed



**Example:** axon nseg = 3

To test spatial resolution

```
forall nseg = nseg*3
and repeat the simulation
```

<b>Category</b>	<b>Variable</b>	<b>Units</b>
Time	$t$	[ms]
Voltage	$v$	[mV]
Current	$i$	[mA/cm <sup>2</sup> ] (density) [nA] (point process)
Concentration	$n, i$ etc.	[mM]
Specific capacitance	$c_m$	[ $\mu$ f/cm <sup>2</sup> ] (density)
Length	diam, $L$	[ $\mu$ m]
Conductance	$g$	[S/cm <sup>2</sup> ] (density) [ $\mu$ S] (point process)
Cytoplasmic resistivity	$R_a$	[ $\Omega$ cm]
Resistance	$r_i$	[10 <sup>6</sup> $\Omega$ ]

## Construction and Use of Models

1. Specify the model ("virtual organism").
2. Specify the user interface ("virtual lab rig").
3. Tests
  - structural integrity
  - spatial grid
  - time steps

## Example: using the GUI to build and exercise a stylized model

1. How to use the CellBuilder to create and manage a model cell.
2. How to use NEURON's graphical tools to make an interface for running simulations.

## Step 0: Conceptualize the task

### Shape

stick figure / detailed

### Channel distribution

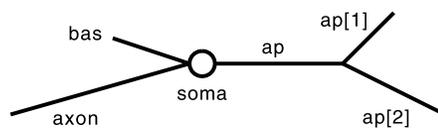
uniform / nonuniform

whole cell / region / individual neurite

### Creation

single cell / use in a network

## Step 1: using the CellBuilder to make a stylized model



Section	L	diam	Biophysics
soma	20 $\mu\text{m}$	20 $\mu\text{m}$	hh
ap[0]	400	2	reduced hh *
ap[1]	300	1	reduced hh *
ap[2]	500	1	reduced hh *
bas	200	3	pas §
axon	800	1	hh

\* -  $g_{\text{nabar\_hh}}$  and  $g_{\text{kbar\_hh}}$  reduced to 10%,  $e_{\text{hh}} = -64$  mV

§ -  $e_{\text{pas}} = -65$  mV

Throughout the cell  $R_a = 160 \Omega \text{ cm}$ ,  $cm = 1 \mu\text{f} / \text{cm}^2$

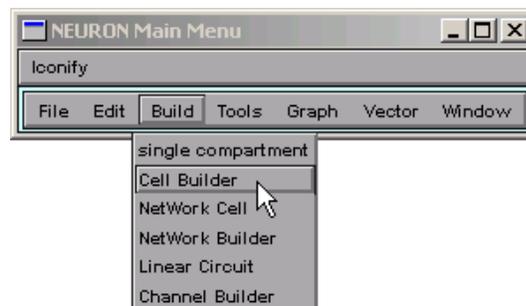
## Launch NEURON with its library of graphical tools

UNIX/Linux `nrngui`

MSWin or OS X

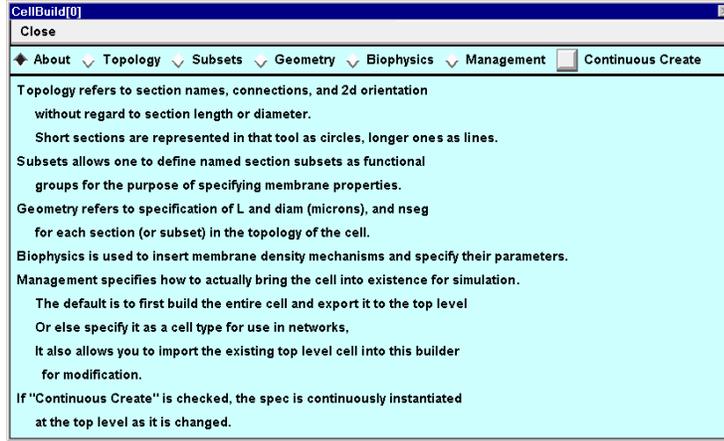


## Bring up a CellBuilder



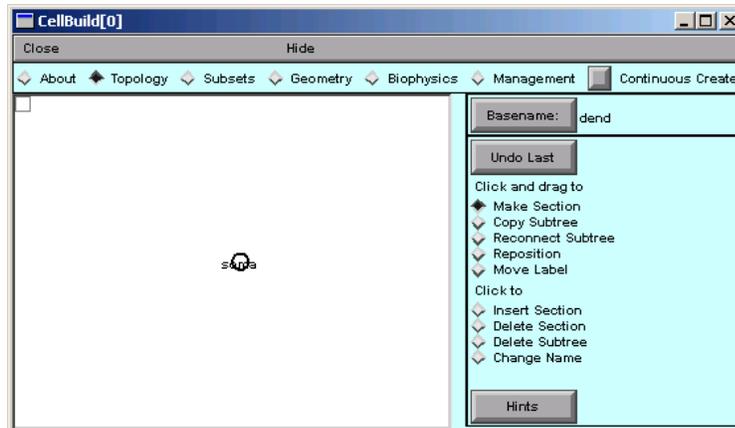
NEURON Main Menu / Build / Cell Builder

# The CellBuilder



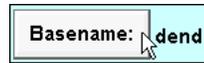
Use buttons from left to right.

# Topology



CB starts with a "soma" section.  
We want to create new sections.

## Specifying the "Basename"



## Making a new section

Place cursor near end of existing section



Click to start new section



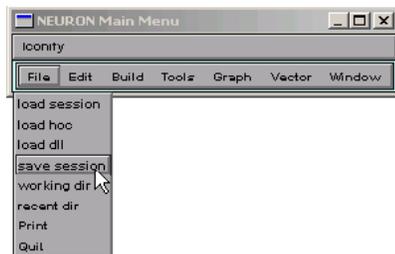
Drag to desired length



Release mouse button

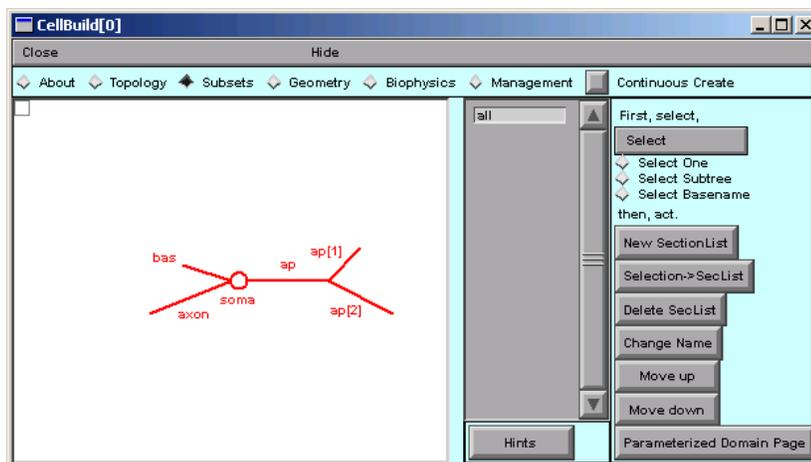


Save your work as you make progress!



NEURON Main Menu / File / save session

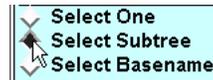
## Subsets



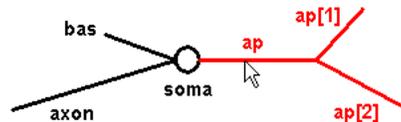
Group sections that have shared properties.  
We want to make an "apicals" subset.

## Making a new subset

Click "Select Subtree"



Click root of apical tree . . .



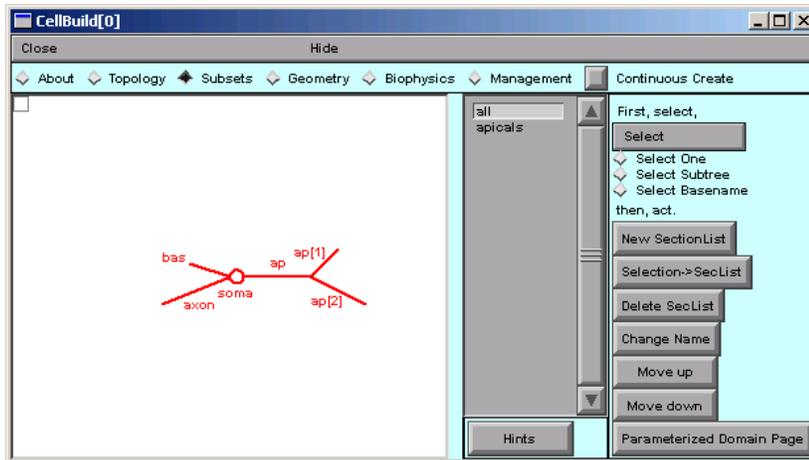
. . . then "New SectionList"



## Making a new subset *continued*



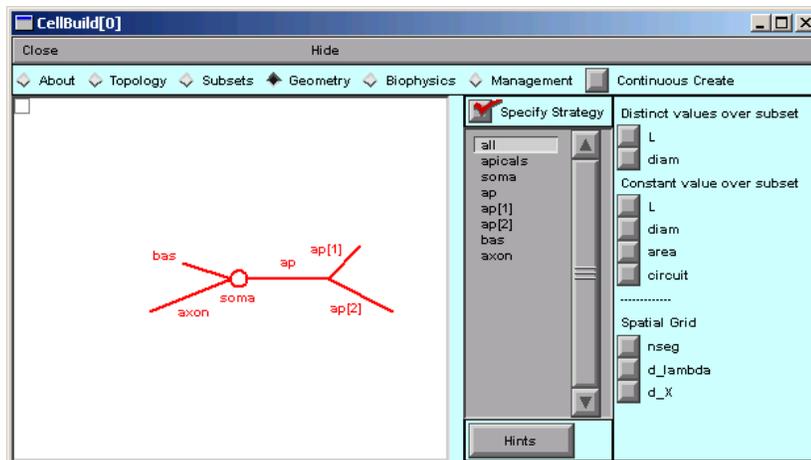
## Subsets finished



Note "apicals".

*Time to save a new session file.*

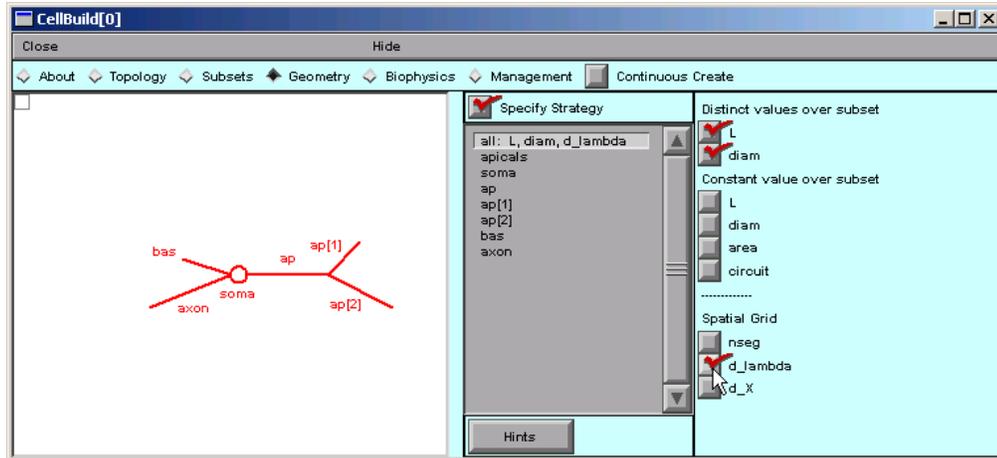
## Geometry



"Specify Strategy" is ON.

A good strategy is a concise strategy.

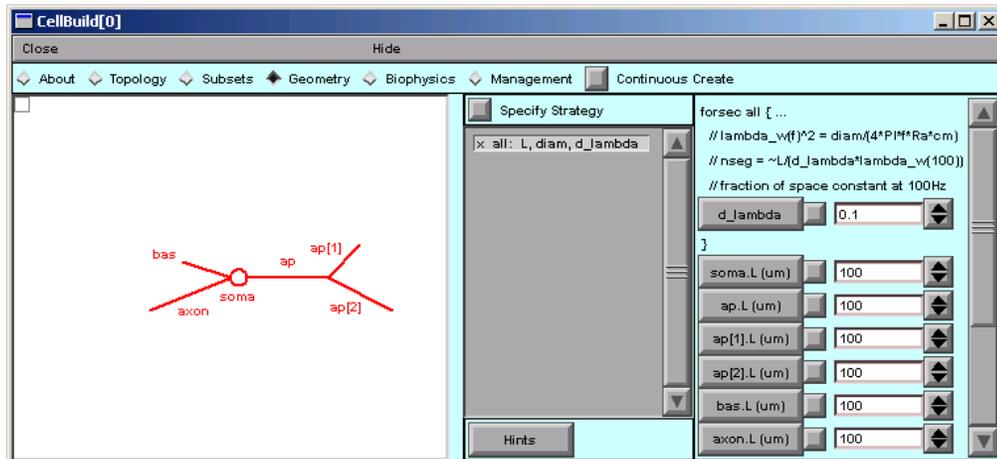
## Geometry strategy



Each section has a different L and diam.

Compartmentalize according to  $\lambda_{100\text{ Hz}}$  (d\_lambda rule).

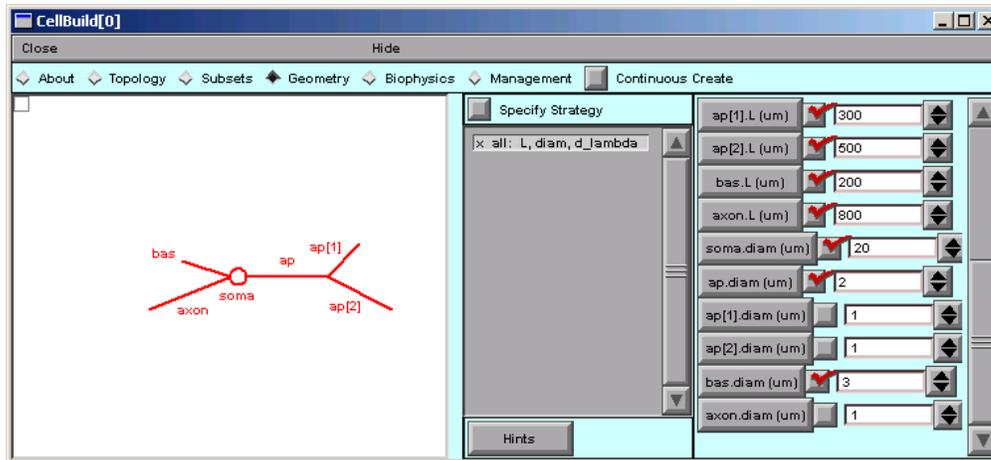
## Implementing geometry strategy



When strategy is complete, turn "Specify Strategy" OFF and start assigning values to parameters.

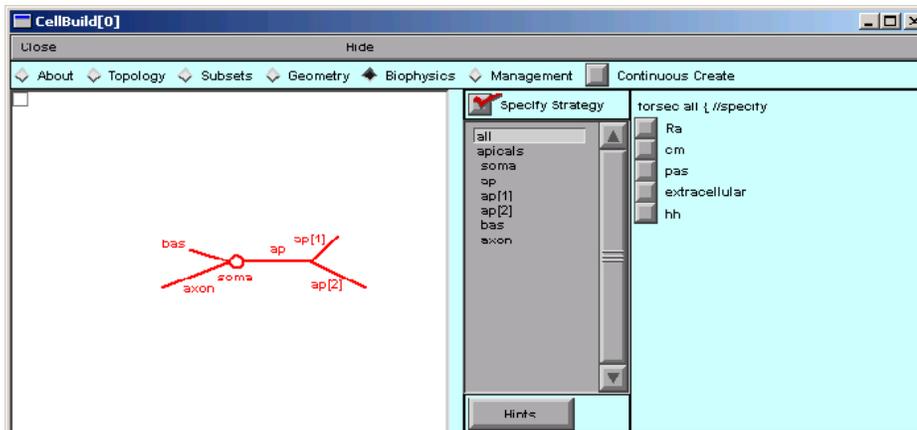
d\_lambda = 0.1 at 100 Hz usually gives good spatial accuracy.

## Implementing geometry *continued*



Set L and diam for all sections.  
*Time to save to a session file!*

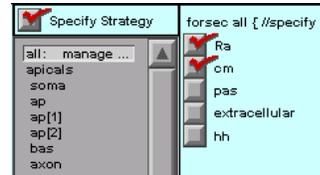
## Biophysics



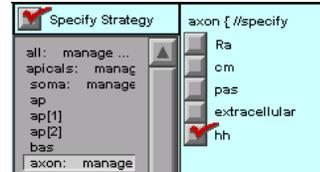
"Specify Strategy" is ON.  
 Base the plan on shared properties.

# Biophysics strategy

Ra and cm are homogeneous



apicals, soma and axon have hh

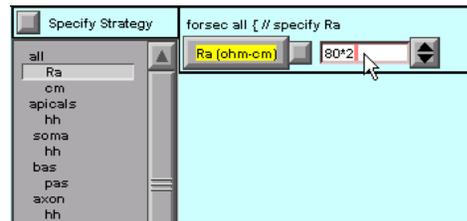


bas has pas

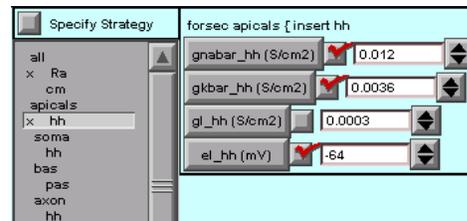


# Implementing biophysics strategy

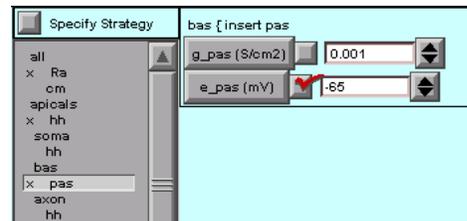
Double Ra



Fix apicals hh params



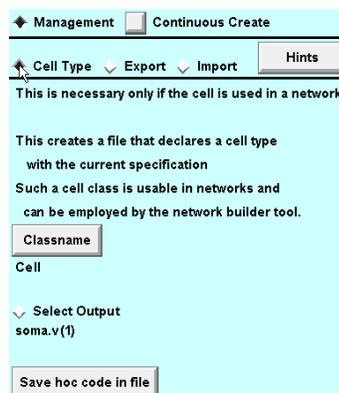
Shift e\_pas in bas



Save another session file!!

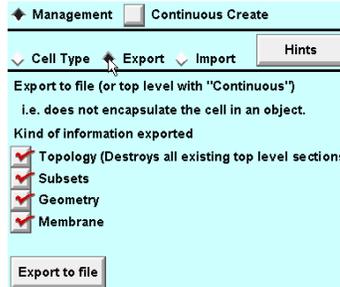
## Management

Option 1: save as a Cell Type  
for use in a network



# Management *continued*

Option 2: save as hoc file



# Management *continued*

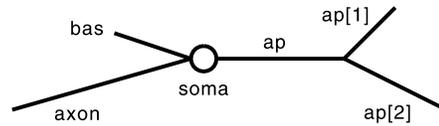
Option 3: export to interpreter

Toggle Continuous Create ON and OFF



or just leave it ON all the time.

## Step 2: creating and using an interface for running simulations



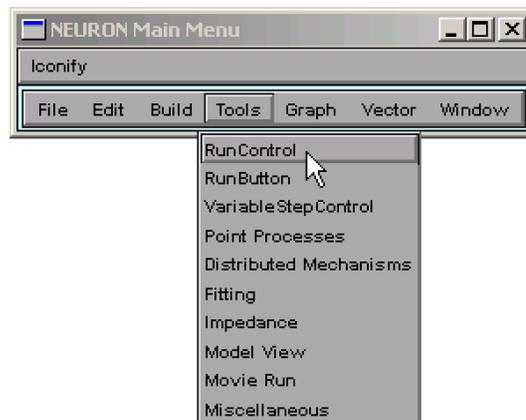
We want to

- attach a stimulating electrode
- evoke an action potential
- show time course of Vm at soma
- show Vm along a path from one end of the cell to the other

We need

- a "Run" button
- graphs to plot results
- a stimulator

## Get a "Run" button



NEURON Main Menu / Tools / RunControl

## RunControl panel

**Init** sets time to 0,  $V_m$  to displayed value, and conductances to steady-state

**Init & Run** does an Init, then starts a simulation

**Stop** interrupts the simulation

**Continue til** runs until displayed time

**Continue for** runs for displayed interval

**Single step** advances by  $1/(\text{Points plotted/ms})$

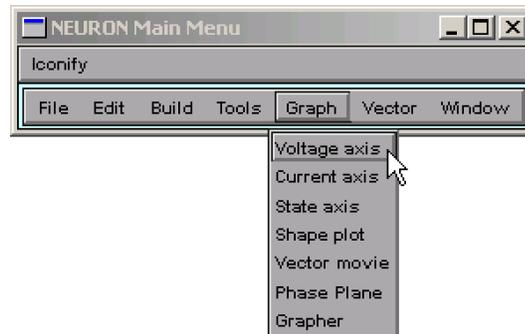
**t** numeric field shows model time

**Tstop** specifies when simulation ends

**dt** is integration time step; must be integer fraction of  $1/(\text{Points plotted/ms})$

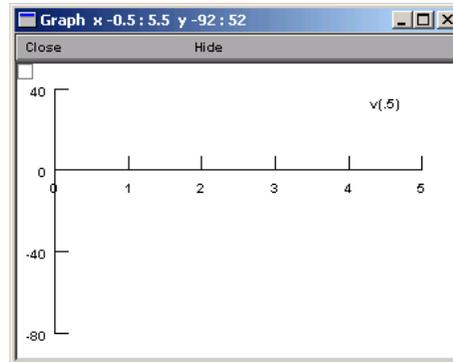
**Points plotted/ms** is plotting interval

We need to plot  $V_m(t)$  at soma



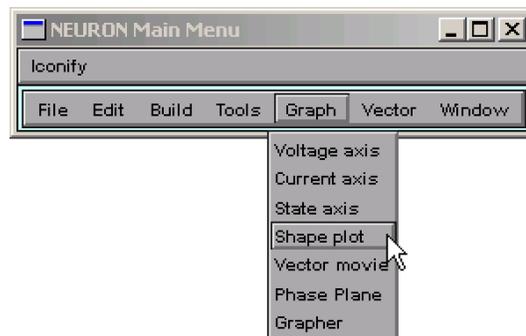
NEURON Main Menu / Graph / Voltage axis

## Graph window



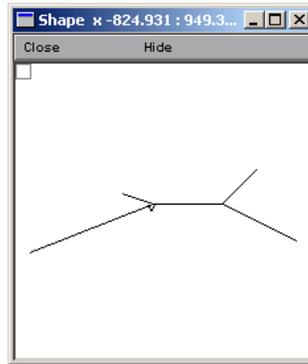
$v(.5)$  is  $V_m$  at middle of default section  
(soma in this example)

## We need to plot $V_m$ along a path



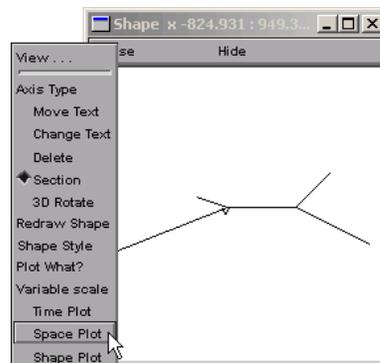
NEURON Main Menu / Graph / Shape plot

## Bringing up a space plot



Use this "shape plot" to create a "space plot".  
Click on its "menu box" . . .

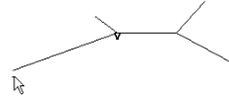
## Bringing up a space plot *continued*



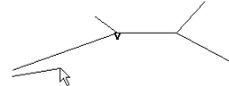
. . . and scroll down to "Space Plot".

## Bringing up a space plot *continued*

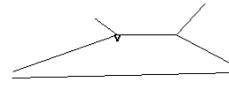
Click just left of the shape



Hold button down while dragging  
from left . . .



. . . to right . . .

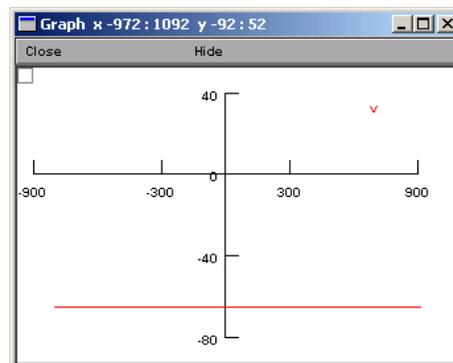


. . . then release button.



This pops up a . . .

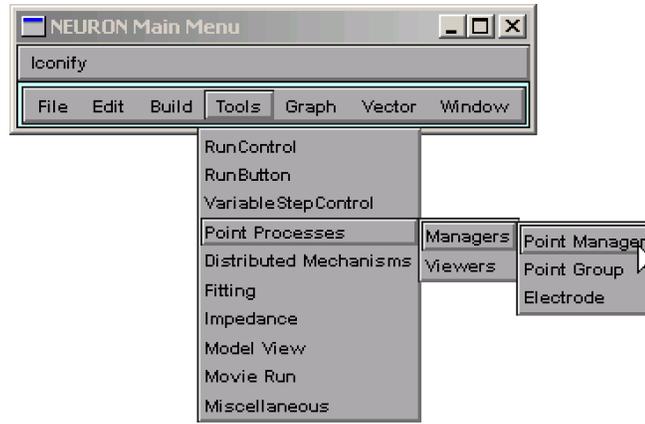
## Space plot



A plot of  $V_m$  vs. distance along a path.

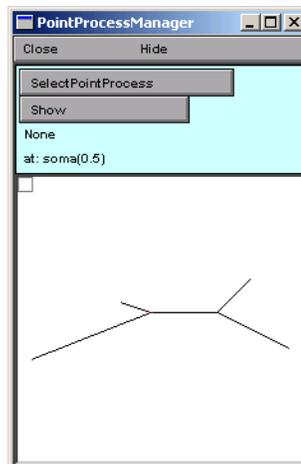
*Better save a session file.*

## We need a stimulator



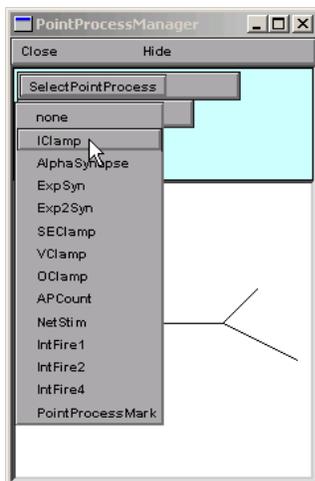
NEURON Main Menu / Tools / Point Processes  
/ Managers / Point Manager

## PointProcessManager window



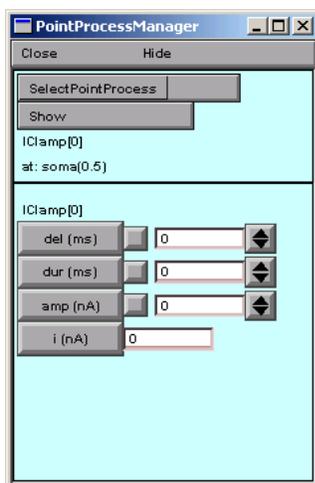
To make this an IClamp . . .

## Creating an IClamp



. . . click on SelectPointProcess  
and scroll down to IClamp.

## IClamp parameter panel



Next: set parameter values.

## Entering values into numeric fields

### Direct entry



Note yellow highlight on button

### Spinner

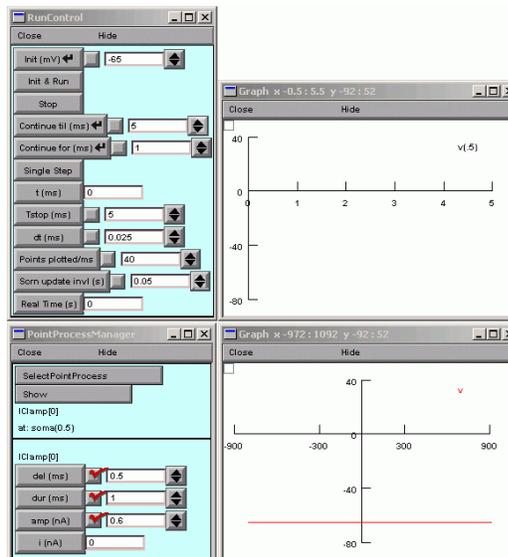


Red check means value has been changed from default

### Mathematical expression

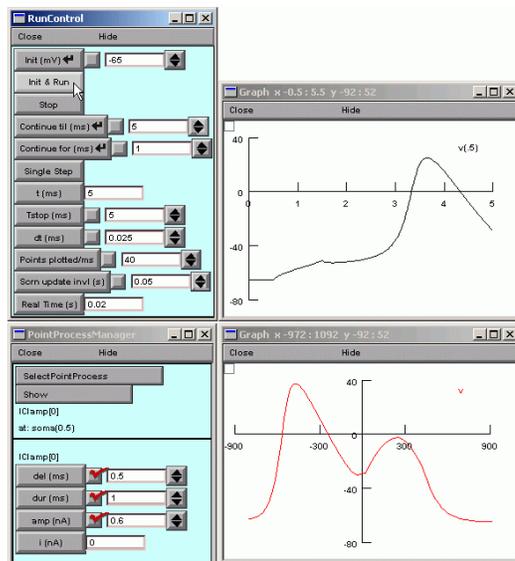


## Our user interface

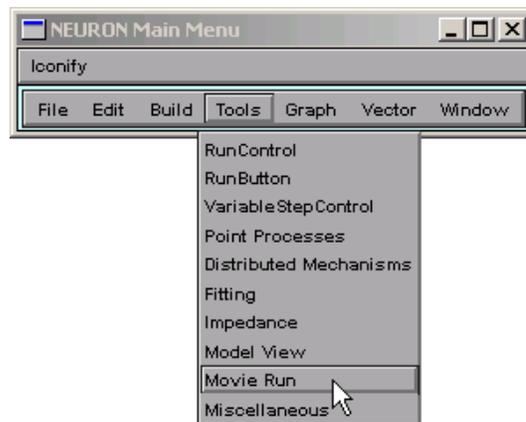


*Time to save to a new session file!*

# It works!



## How to get nice space plot "movies"



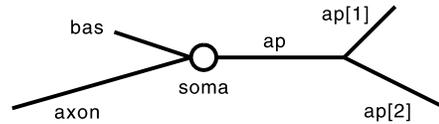
NEURON Main Menu / Tools / Movie Run

## Space plot "movies" *continued*



Movie Run / Init & Run

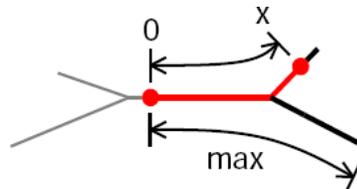
## What if hh is nonuniform over the apicals?



Suppose  $g_{nabar\_hh}$ ,  $g_{kbar\_hh}$ , and  $g_{l\_hh}$  all decrease linearly with distance from the origin of the apical tree.

Details:

1. All have full density at origin of apical tree.
2. Density falls to 0% at most the most distant termination.
3. For uniform -65 mV resting potential,  $e_{l\_hh} = -54.3$  mV.



This example:

$$g_{nabar\_hh} = 0.12 * (1 - p) \text{ where } p = L_{0x}/L_{max}$$

(normalized path distance from location x to origin 0 of apical tree)

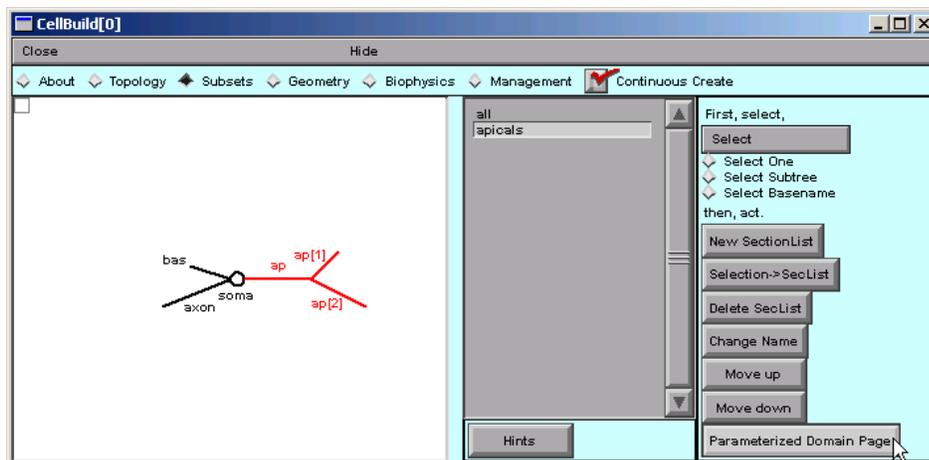
The general task:  $param = f(p)$ , where f can be any function and p is one of these "distance metrics":

- path length from a reference point
- radial distance from a reference point
- distance from a plane ("3D projection onto a line")

An equivalent hoc idiom:

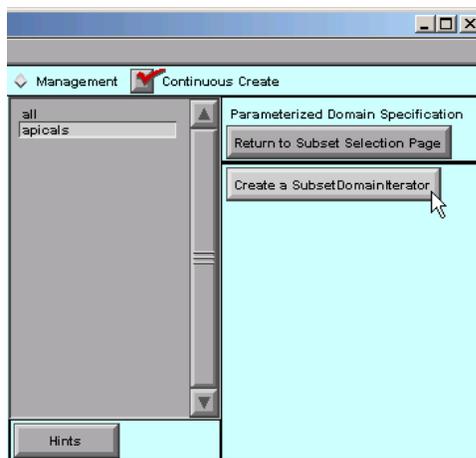
$$\text{forsec subset for } (x,0) \{ \text{rangevar\_suffix}(x) = f(p(x)) \}$$

## Setting up a SubsetDomainIterator



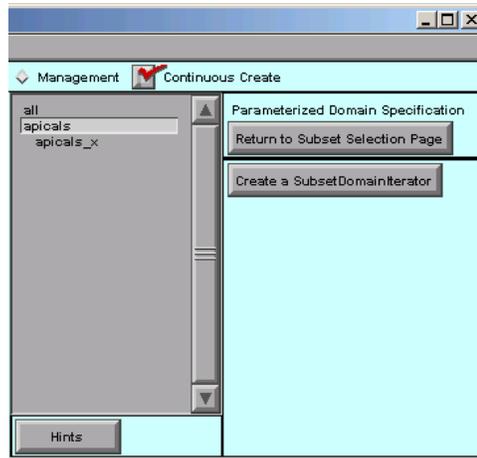
Select a subset, then click on  
"Parameterized Domain Page"

## SubsetDomainIterator *continued*



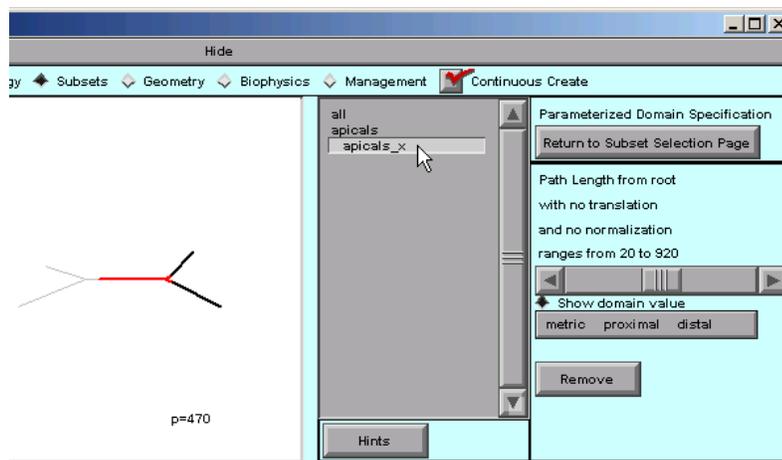
Click on "Create a SubsetDomainIterator"

## SubsetDomainIterator *continued*



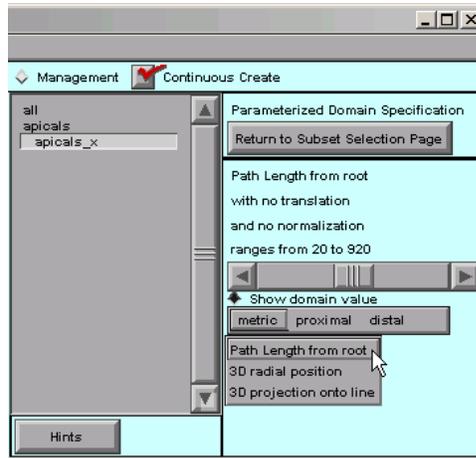
Note "apicals\_x" in middle panel.  
Click on it . . .

## SubsetDomainIterator *continued*



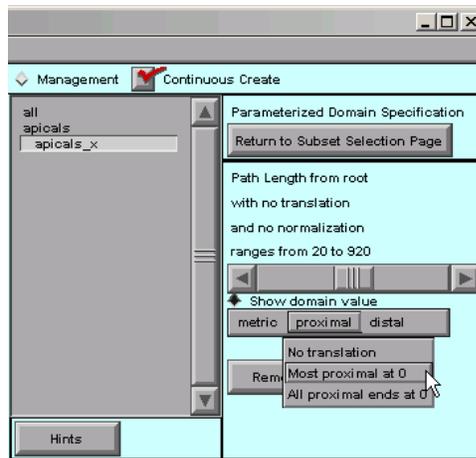
. . . to see controls for specifying the distance metric.

## SubsetDomainIterator *continued*



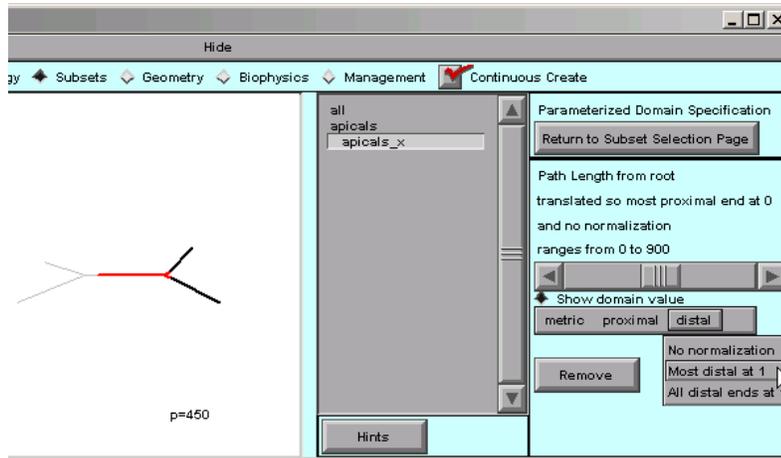
"metric" offers the three basic choices

## SubsetDomainIterator *continued*



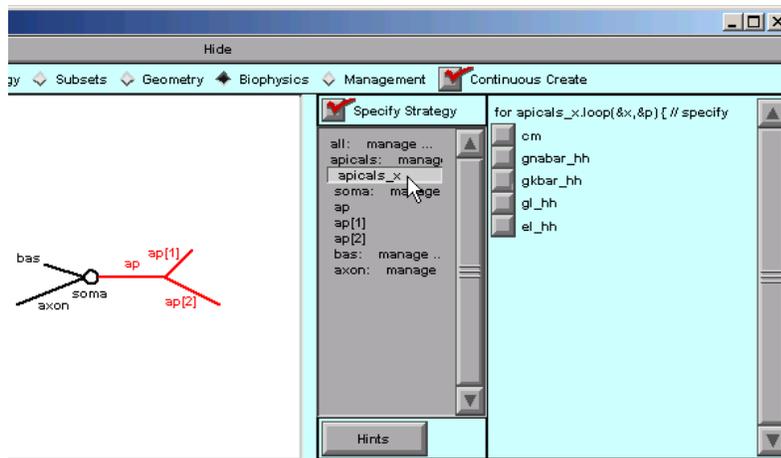
proximal / Most proximal at 0  
 makes distance start at root of apical tree

## SubsetDomainIterator *continued*



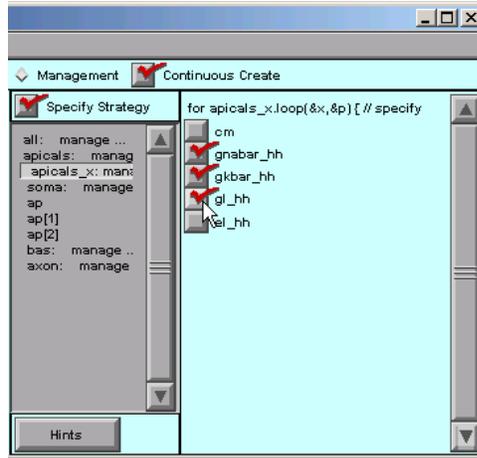
distal / Most distal at 1  
finishes "normalization" of distance

## Back to Biophysics Strategy



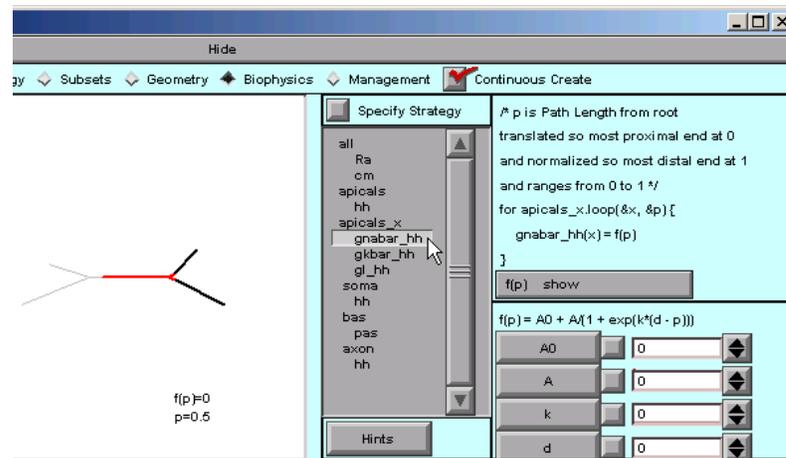
Click on apicals\_x,  
then select the parameters it will control.

## Biophysics Strategy *continued*



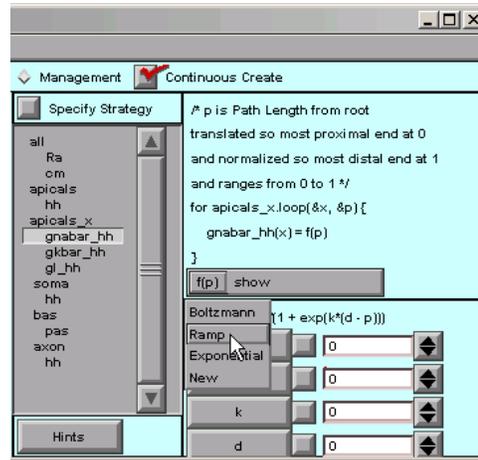
We want `gnabar_hh`, `gkbar_hh`, and `gl_hh` to be inhomogeneous.

## Implement the strategy



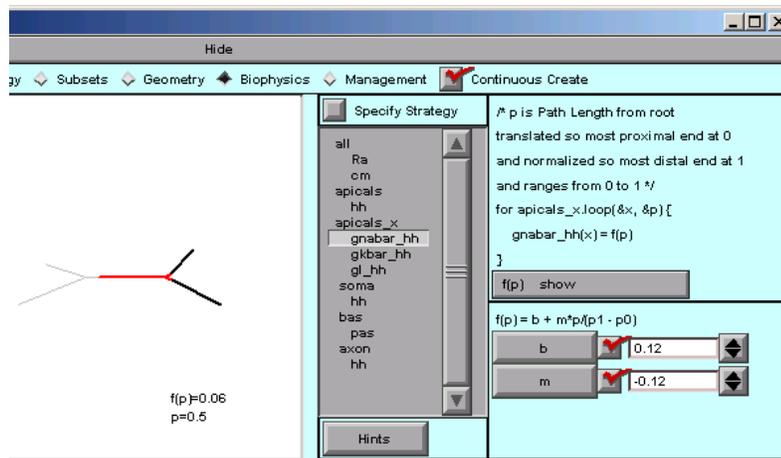
Click on one of the inhomogeneous parameters. Note that default  $f(\ )$  is Boltzmann.

## Implement the strategy *continued*



$f(p)$  / Ramp  
selects linear function

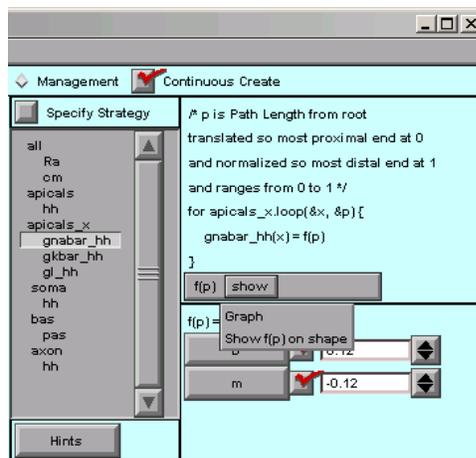
## Implement the strategy *continued*



After setting intercept  $b$  and slope  $m$  for `gnabar_hh`

Save another session file!!

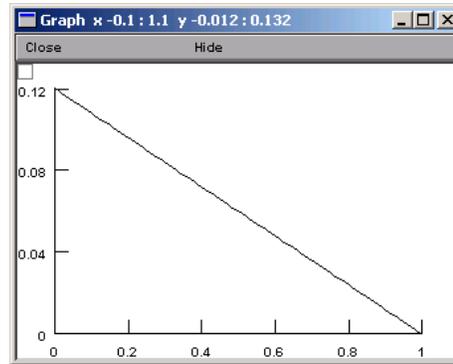
Verify the implementation



show / graph

show / Show f(p) on shape

## Verify the implementation *continued*



"show / graph" results:

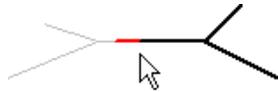
x axis: normalized distance from origin of apicals

y axis: gnabar\_hh

## Verify the implementation *method 2*

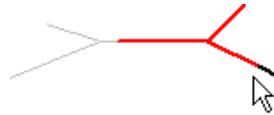
1. show / Show f(p) on shape
2. Click next to shape and drag . . .

. . . from left . . .



f(p)=0.105447  
p=0.121278  
ap [0.272875]

. . . to right . . .

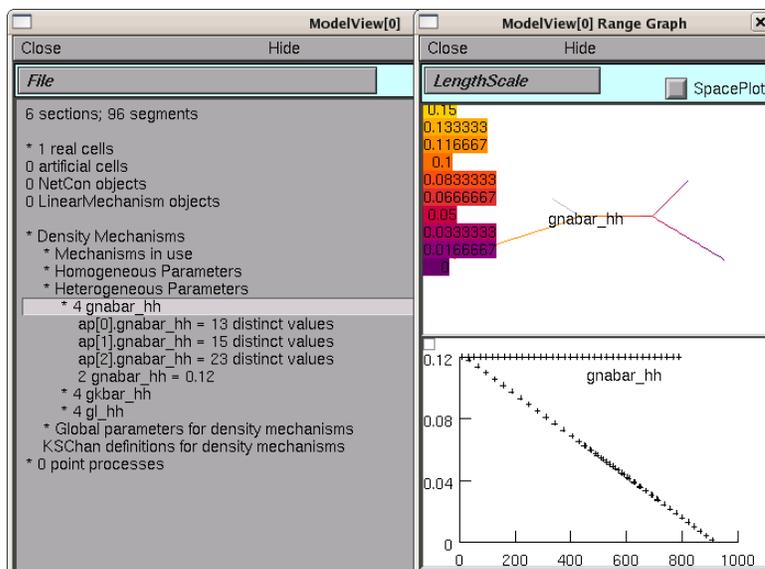


f(p)=0.0204694  
p=0.829422  
ap[2] [0.692959]

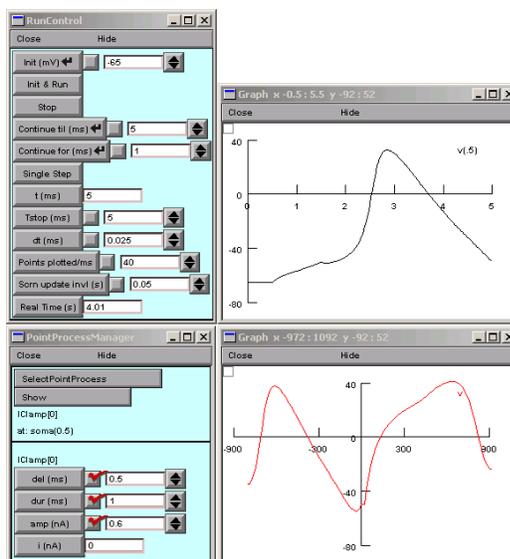
. . . while watching the values of p and f(p)

# Verify the implementation *method 3*

NEURON Main Menu / Tools / Model View



# A simulation with the revised model





## The Channel Builder

Voltage- and ligand-gated channels

Kinetic schemes, HH-style differential equations

Optional stochastic gating mode for point processes

Faster than equivalent NMODL mechanisms

Much easier to use than writing NMODL code

Limited to channels

NMODL needed for pumps, buffers, diffusion, event-driven synaptic mechanisms, artificial spiking cells

Tutorial: see Documentation at NEURON's home page  
<http://www.neuron.yale.edu/>

## Conceptualize the task

Ion selectivity

I/V relationship ohmic / GHK (constant field)

Description of dynamics HH style / kinetic scheme

Gates independent identical subunits  
fractional openness

Sensitivity voltage / ligand

Transition style alpha, beta / inf, tau  
functions / tables

## Implementing the HH $i_{Na}$ with the Channel Builder

$i_{Na} = g_{Na} (V - E_{Na})$  where

$$g_{Na} = gbar_{Na} m^3 h$$

$$gbar_{Na} = 0.12 \text{ S/cm}^2$$

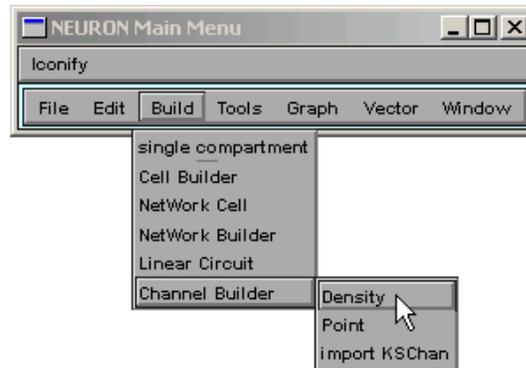
$m$  and  $h$  are described by DEs of the form

$$dx/dt = \alpha (1 - x) - \beta x$$

## How to proceed

1. Bring up a Channel Builder
2. Specify channel's basic properties
3. Specify channel gating
  - states
  - transitions (if a kinetic scheme)
  - effects of voltage and ligands

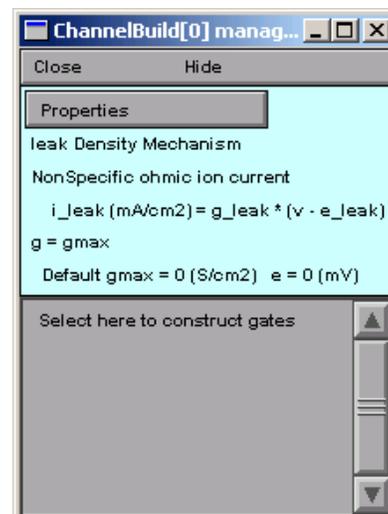
# 1. Bring up a Channel Builder



NEURON Main Menu / Build  
/ Channel Builder / Density

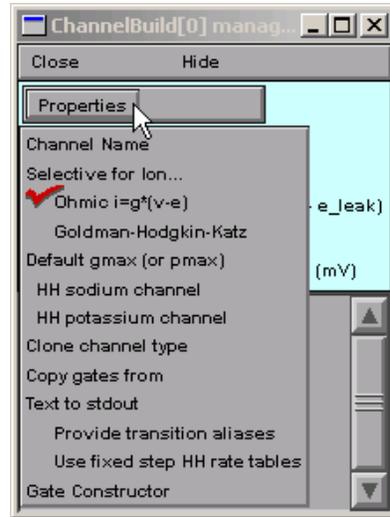
## The Channel Builder

We need to change its name,  
ion selectivity,  
default conductance,  
and equilibrium potential



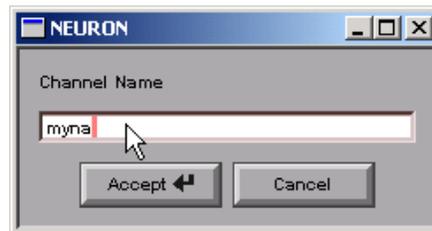
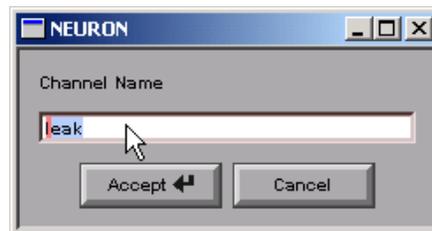
## 2. Specify channel's basic properties

Click on Properties,  
then select item to change



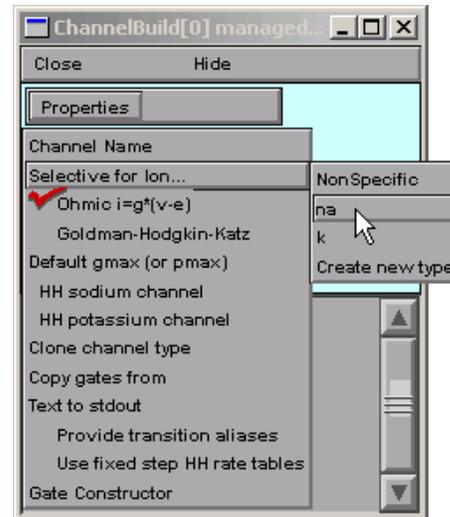
## Name

Properties / Channel Name  
Then change leak to myna



## Ion selectivity

Properties  
/ Selective for Ion... / na



## Default conductance and equilibrium potential

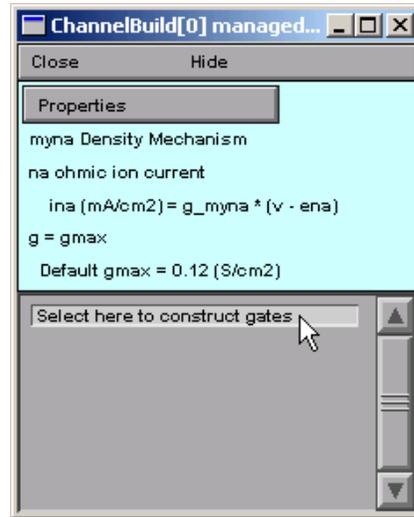
Properties / Default gmax  
Specify 0.12 S/cm<sup>2</sup>



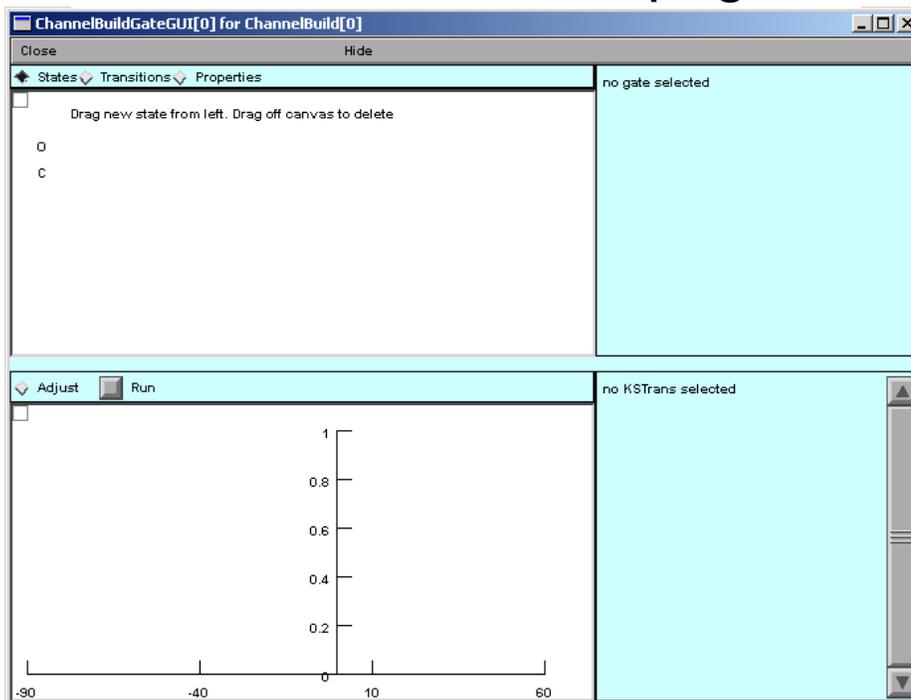
Equilibrium potential:  
na has its own ena,  
so nothing to do!

### 3. Specify channel gating

"Select here to construct gates"

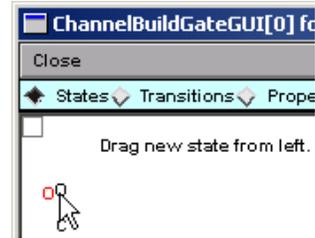


### "GateGUI": States page



## Spawn states

Click and drag O ("open")  
from palette . . .



. . . to canvas.



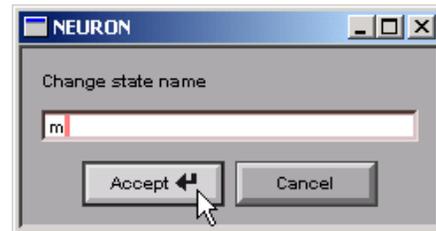
Repeat for C ("closed")

## Rename states

Click O without dragging



Change to m



Change C to h



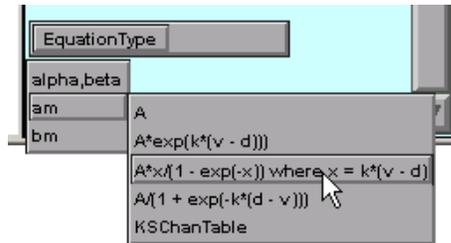
## "GateGUI": Properties page

## Set m exponent

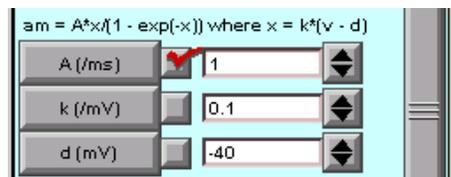
Change Power to 3

# Specify voltage dependence of am and bm

Choose functional form for am



Set parameter values



Do same for bm

ChannelBuildGateGUI[0] for ChannelBuild[0]

Close Hide

States Transitions Properties

Select hh state or ks transition to change properties

m h

**m properties after configuring am and bm**

$m^3$   
 $m^3 = am^3(1 - m) - bm^3m$

Power  3

Fractional Conductance

m fraction 1

---

Adjust Run

m ↔ m (a, b) (KSTrans[1])

Display inf, tau

am =  $A^3x^3/(1 - \exp(-x))$  where  $x = k^3(v - d)$

A (/ms) 1

k (/mV) 0.1

d (mV) -40

bm =  $A^3\exp(k^3(v - d))$

A (/ms)  4

k (/mV)  -0.055556

d (mV)  -65

EquationType

## Testing

# NMODL

NEURON Model Description Language

## Add new membrane mechanisms to NEURON

### Density mechanisms

- Distributed Channels
- Ion accumulation

### Point Processes

- Electrodes
- Synapses

### Described by

- Differential equations
- Kinetic schemes
- Algebraic equations

### Benefits

- Specification only -- independent of solution method.
- Efficient -- translated into C.
- Compact
  - One NMODL statement -> many C statements.
  - Interface code automatically generated.
- Consistent ion current/concentration interactions.
- Consistent Units

# NMODL general block structure

## What the model looks like from outside

```
NEURON {
    SUFFIX kchan
    USEION k READ ek WRITE ik
    RANGE gbar, ...
}
```

## What names are manipulated by this model

```
UNITS { (mV) = (millivolt) ... }
PARAMETER { gbar = .036 (mho/cm2) <0, 1e9>... }
STATE { n ... }
ASSIGNED { ik (mA/cm2) ... }
```

## Initial default values for states

```
INITIAL {
    rates(v)
    n = ninf
}
```

## Calculate currents (if any) as function of v, t, states

(and specify how states are to be integrated)

```
BREAKPOINT {
    SOLVE deriv METHOD cnexp
    ik = gbar * n^4 * (v - ek)
}
```

## State equations

```
DERIVATIVE deriv {
    rates(v)
    n' = (ninf - n)/ntau
}
```

## Functions and procedures

```
PROCEDURE rates(v(mV)) {
    ...
}
```

# UNIX

```
nrnivmodl
nrngui
```

# MSWIN



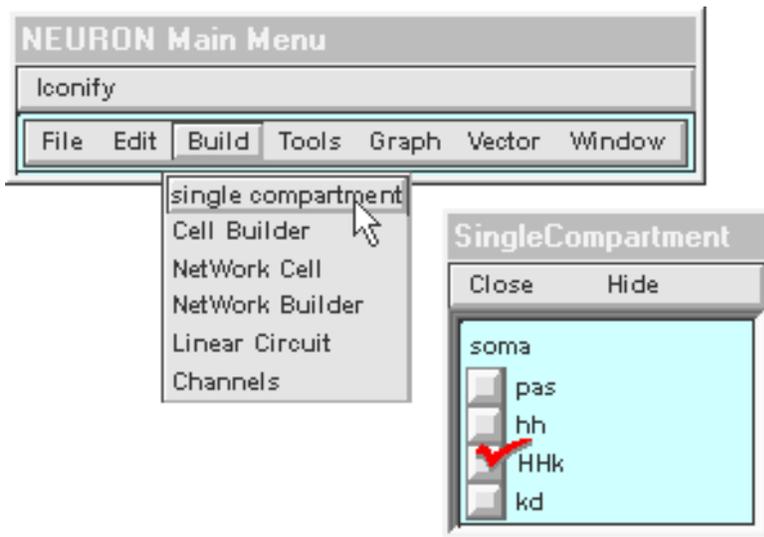
mknrndll



nrngui



Select NEURON Main Menu / Build / single compartment



## Density mechanism

## Point Process

### NMODL

```

NEURON {
  SUFFIX leak
  NONSPECIFIC_CURRENT i
  RANGE i, e, g
}

PARAMETER {
  g = .001 (mho/cm2) <0, 1e9>
  e = -65 (millivolt)
}

ASSIGNED {
  i (milliamp/cm2)
  v (millivolt)
}

BREAKPOINT {
  i = g*(v - e)
}

```

```

NEURON {
  POINT_PROCESS Shunt
  NONSPECIFIC_CURRENT i
  RANGE i, e, r
}

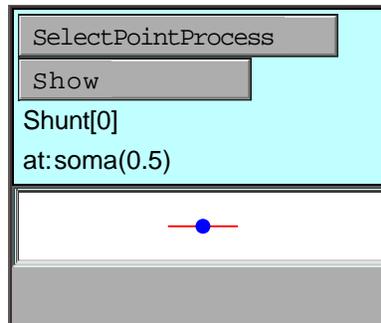
PARAMETER {
  r = 1 (gigaohm) <1e-9,1e9>
  e = 0 (millivolt)
}

ASSIGNED {
  i (nanoamp)
  v (millivolt)
}

BREAKPOINT {
  i = (.001)*(v - e)/r
}

```

### GUI



### Interpreter

```

soma {
  insert leak
  g_leak = .0001
}
print soma.i_leak(.5)

```

```

objref s
soma s = new Shunt(.5)
s.r = 2

```

## Ion Channel

```

NEURON {
  USEION k READ ek WRITE ik
}
BREAKPOINT {
  SOLVE states METHOD cnexp
  ik = gbar*n*n*n*n*(v - ek)
}
DERIVATIVE states {
  rate(v*1(/mV))
  n' = (inf - n)/tau
}

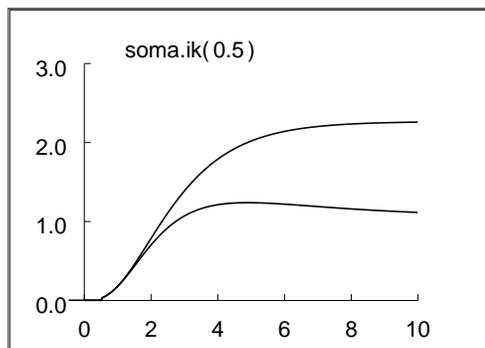
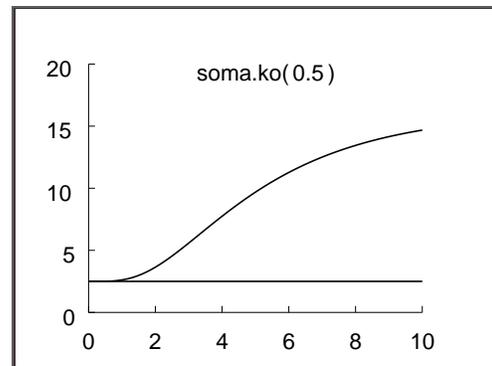
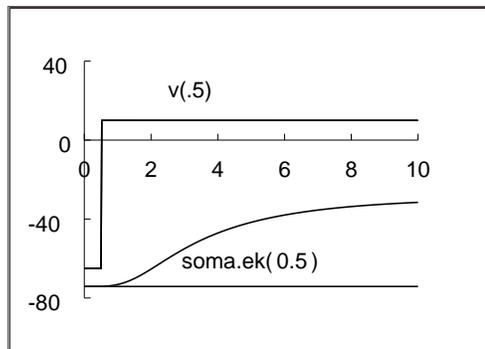
```

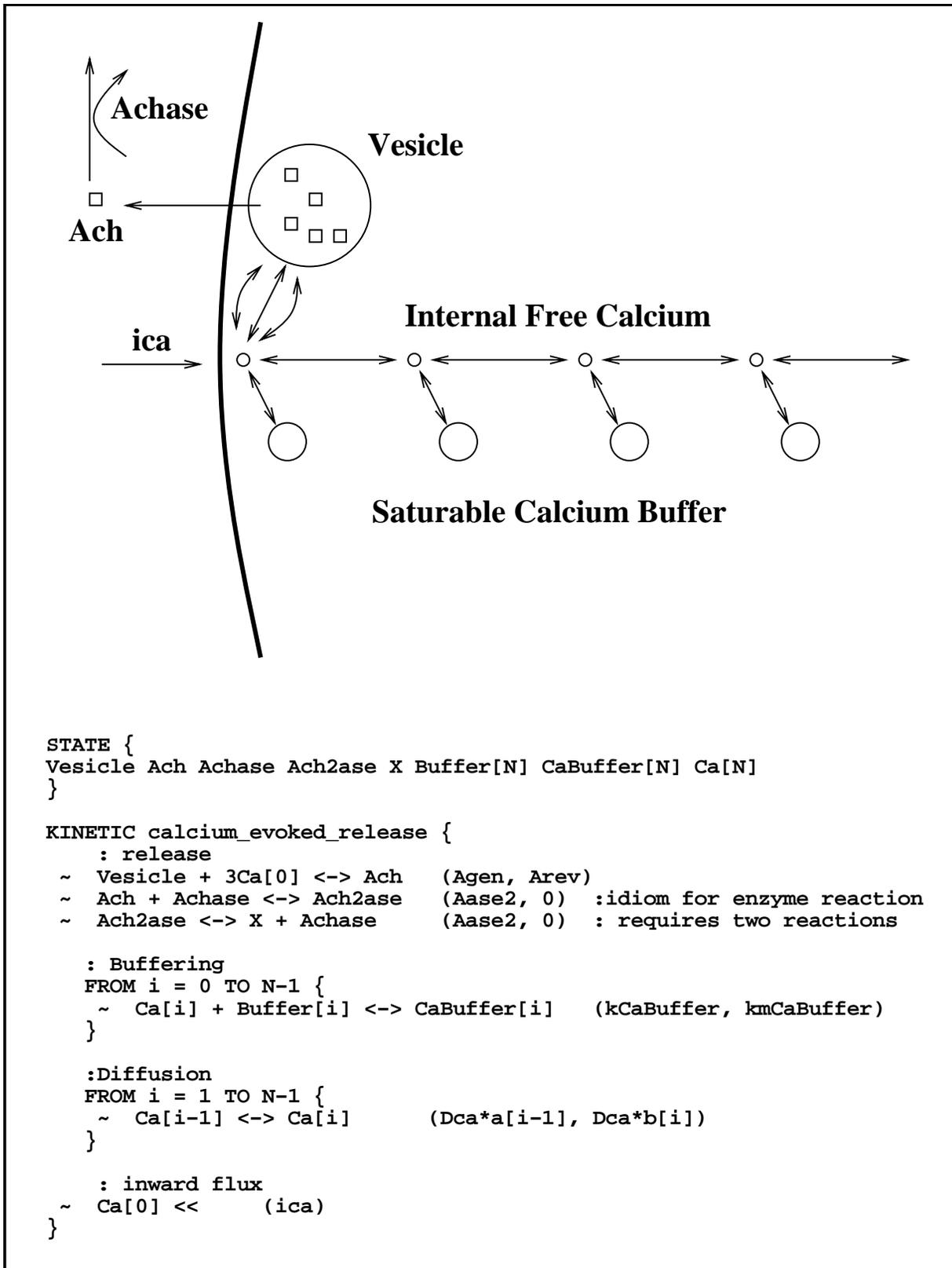
## Ion Accumulation

```

NEURON {
  USEION k READ ik WRITE ko
}
BREAKPOINT {
  SOLVE state METHOD cnexp
}
DERIVATIVE state {
  ko' = ik/fhspace/F*(1e8)
  + k*(kbath - ko)
}

```





## UNITS Checking

```

NEURON { POINT_PROCESS Shunt ... }

PARAMETER {
    e = 0 (millivolt)
    r = 1 (gigaohm) <1e-9,1e9>
}

ASSIGNED {
    i (nanoamp)
    v (millivolt)
}

BREAKPOINT {
    i = (v - e)/r
}

```

Units are incorrect in the "i = ..." current assignment.  
The output from

```

modlunit shunt

is:

```

```

Checking units of shunt.mod
The previous primary expression with units: 1-12 coul/sec
is missing a conversion factor and should read:
    (0.001)*()
at line 14 in file shunt.mod
    i = (v - e)/r<>

```

To fix the problem replace the line with:

```

    i = (.001)*(v - e)/r

```

---

### What conversion factor will make the following consistent?

$$n_{ai}' = i_{na} / \text{FARADAY} * (c/\text{radius})$$

$$(\text{uM/ms}) \quad (\text{mA/cm}^2) / (\text{coulomb/mole}) / (\text{um})$$



## The Linear Circuit Builder

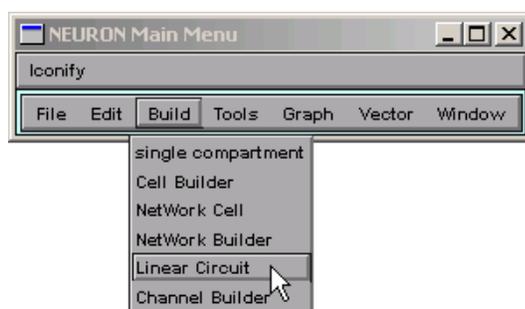
For building models that have linear circuit elements  
and may also involve neurons

Circuit elements include ground, current & voltage  
source, R, C, op amp

Potential applications include

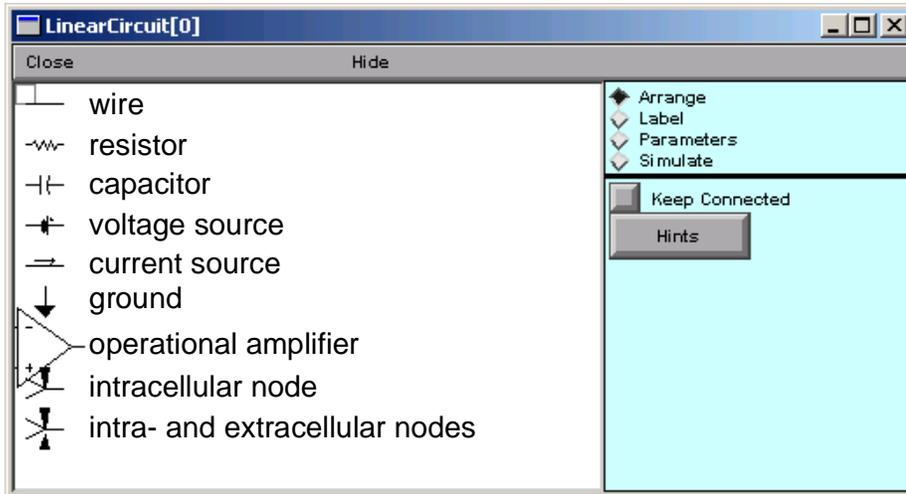
- effects and compensation of electrode R & C
- two-electrode voltage clamp
- ohmic and nonlinear gap junctions

### 1. Bring up a Linear Circuit Builder



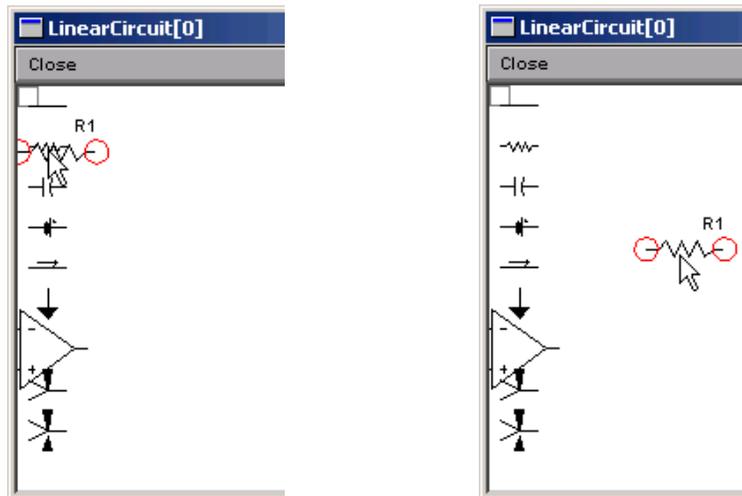
NEURON Main Menu / Build / Linear Circuit

# The Linear Circuit Builder



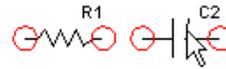
## Arrange: spawn components

Click on palette and drag onto canvas

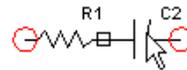


## Arrange: connect components

Click and drag to overlap red circles



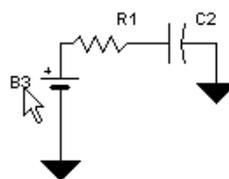
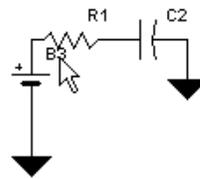
Black square is "solder joint"



Pull apart to break connection

## Label: move labels

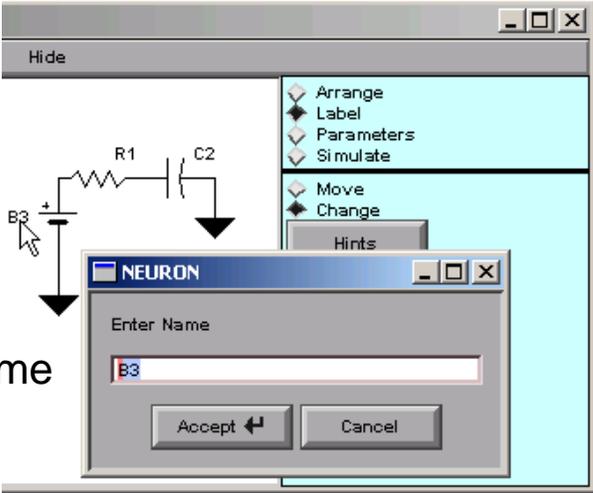
Click and drag to new location



## Label: change labels 1

Click on a label . . .

. . . to change its name

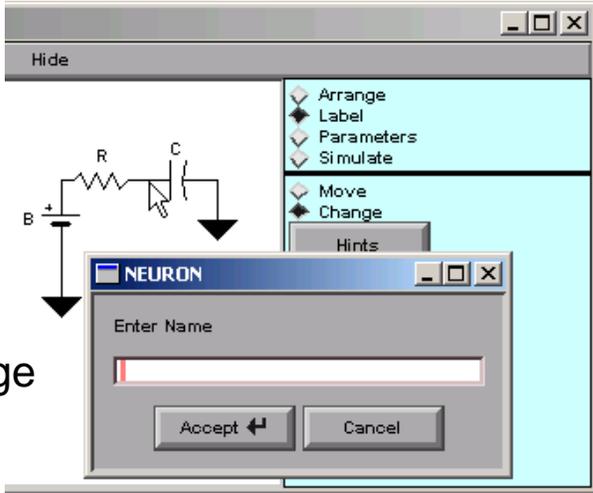


The screenshot shows a circuit diagram with a battery labeled B3, a resistor labeled R1, and a capacitor labeled C2. A context menu is open over the B3 label, showing options: Arrange, Label, Parameters, Simulate, Move, Change, and Hints. A dialog box titled 'NEURON' is open, with the text 'Enter Name' and a text field containing 'B3'. The dialog box has 'Accept' and 'Cancel' buttons.

## Label: change labels 2

Click on a node . . .

. . . to label a voltage



The screenshot shows a circuit diagram with a battery labeled B, a resistor labeled R, and a capacitor labeled C. A context menu is open over a node in the circuit, showing options: Arrange, Label, Parameters, Simulate, Move, Change, and Hints. A dialog box titled 'NEURON' is open, with the text 'Enter Name' and an empty text field. The dialog box has 'Accept' and 'Cancel' buttons.

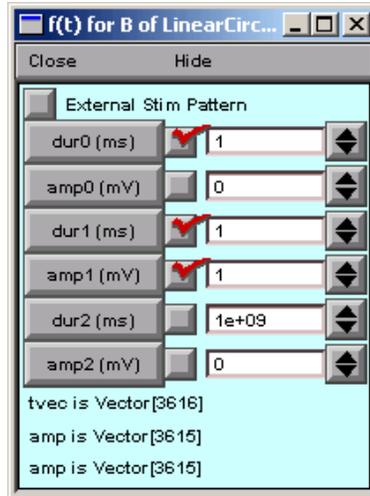
## Parameters: non-source elements

Click on "Parameters"

## Parameters: signal sources

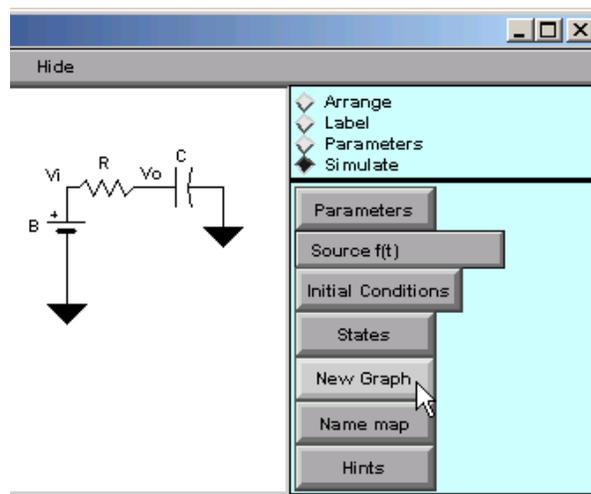
Source  $f(t)$  / B

## Parameters: signal sources *continued*



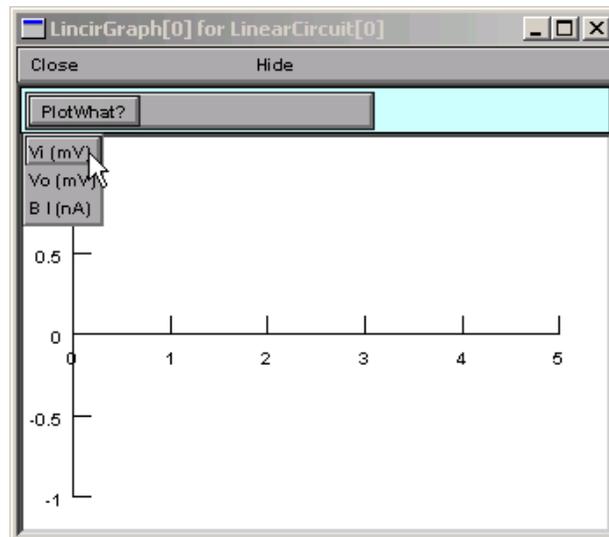
Configured

## Simulate: creating a graph



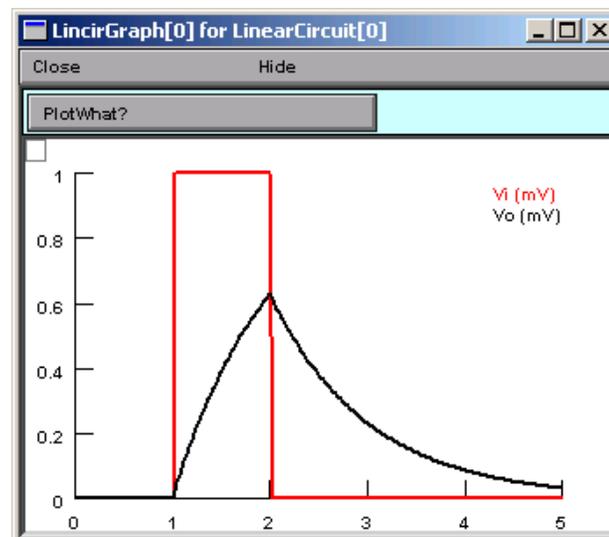
New Graph

## Simulate: specifying what to plot



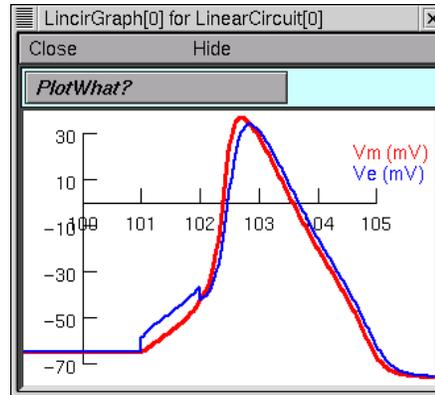
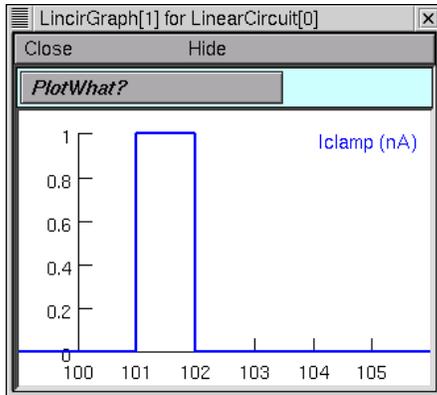
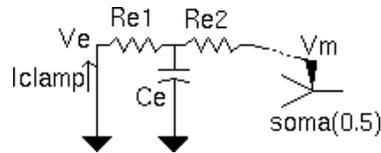
PlotWhat? / *variable\_label*

## Simulate: simulation results

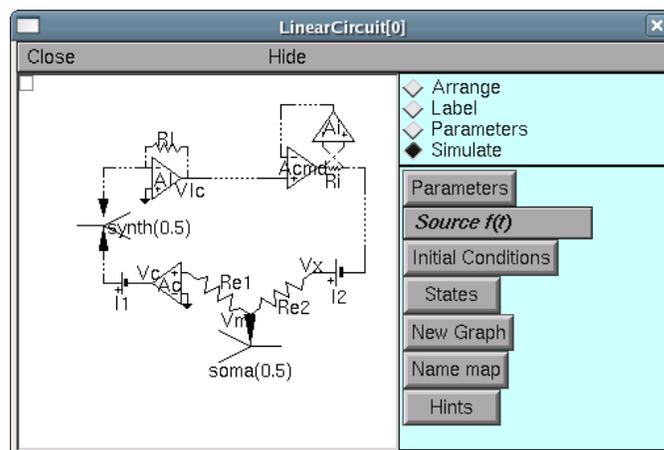


After minor cosmetic changes

## Patch clamp with electrode R and C



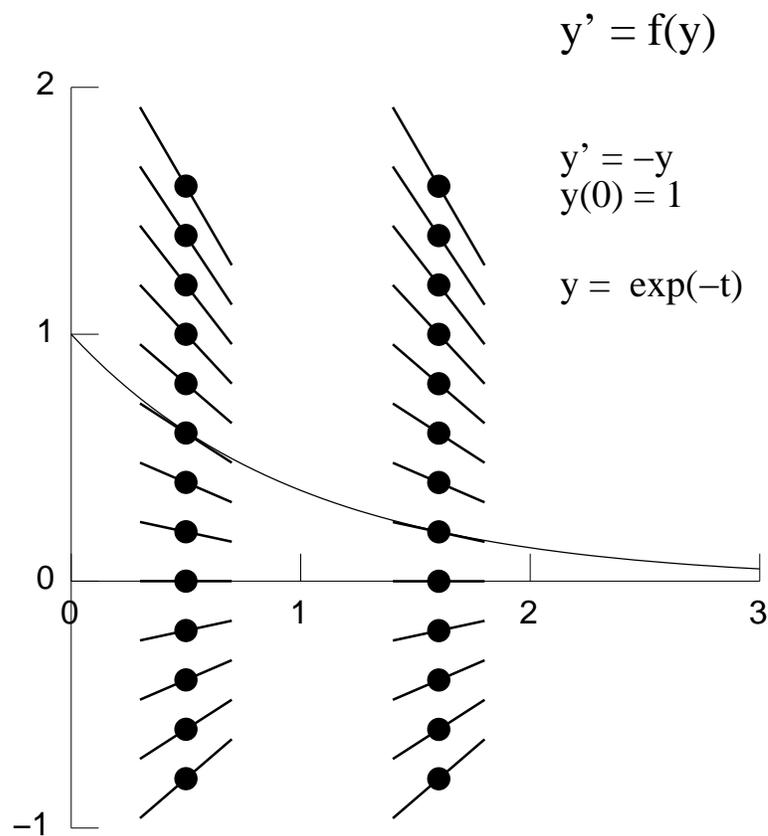
## NEURON demo: dynamic clamp



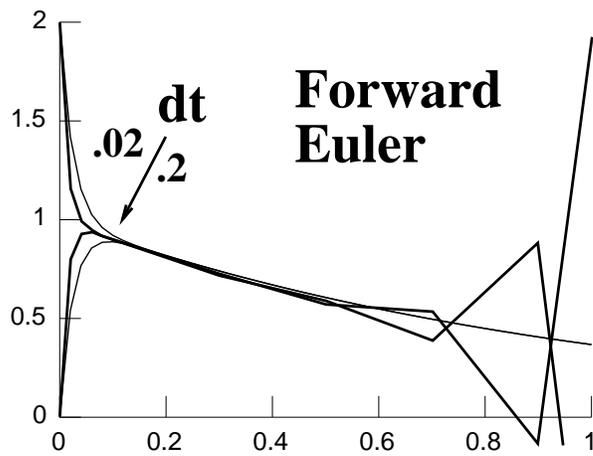
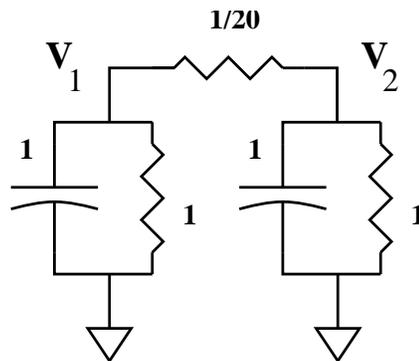
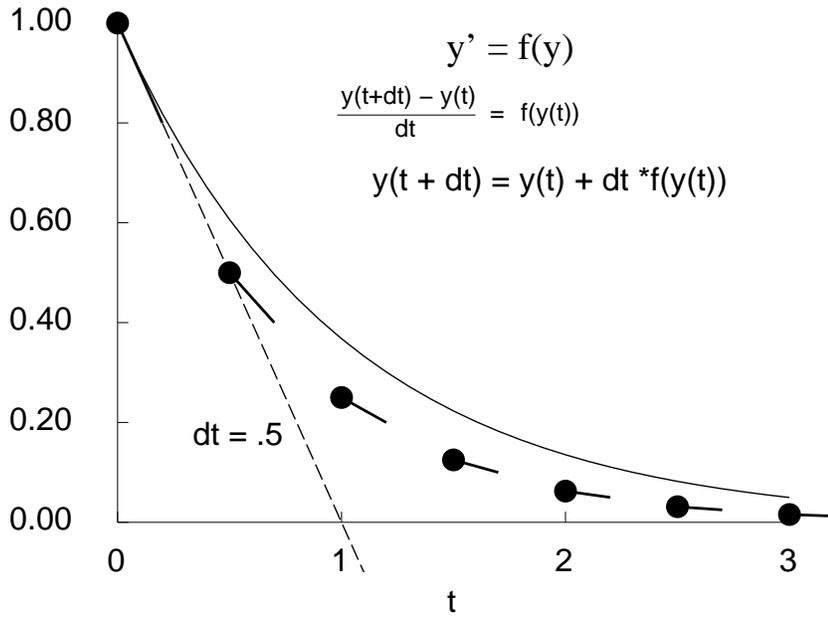
# Compartmental Modeling

Not much mathematics required.

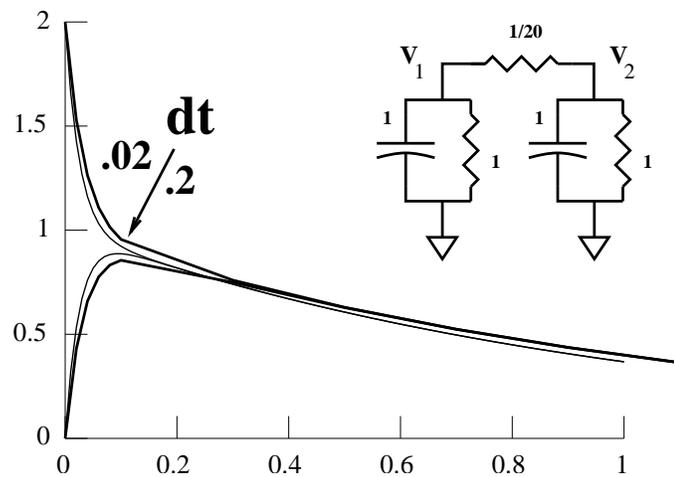
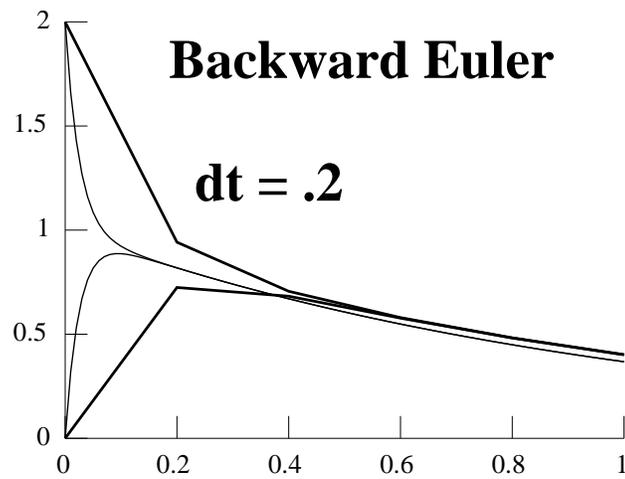
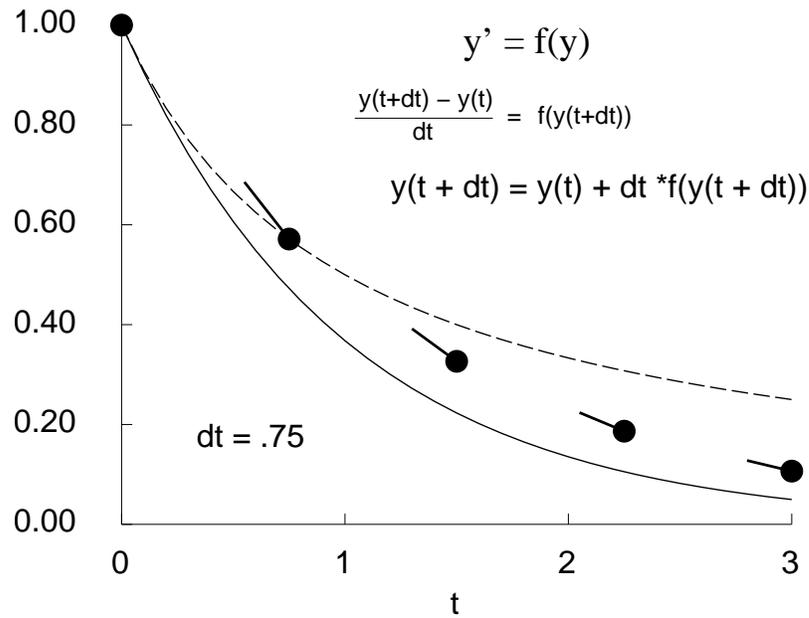
Good judgment essential!



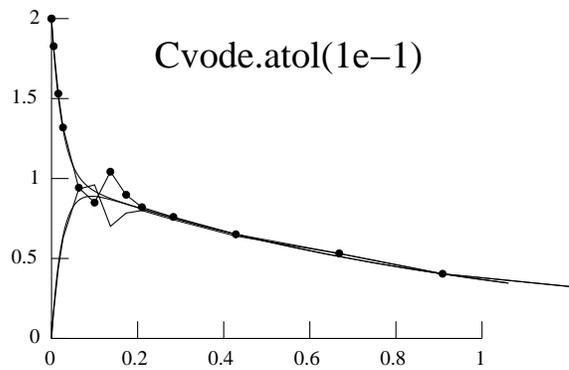
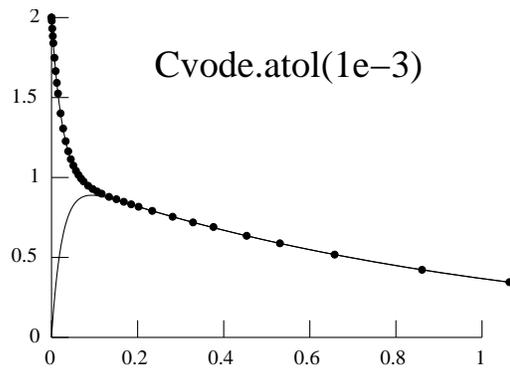
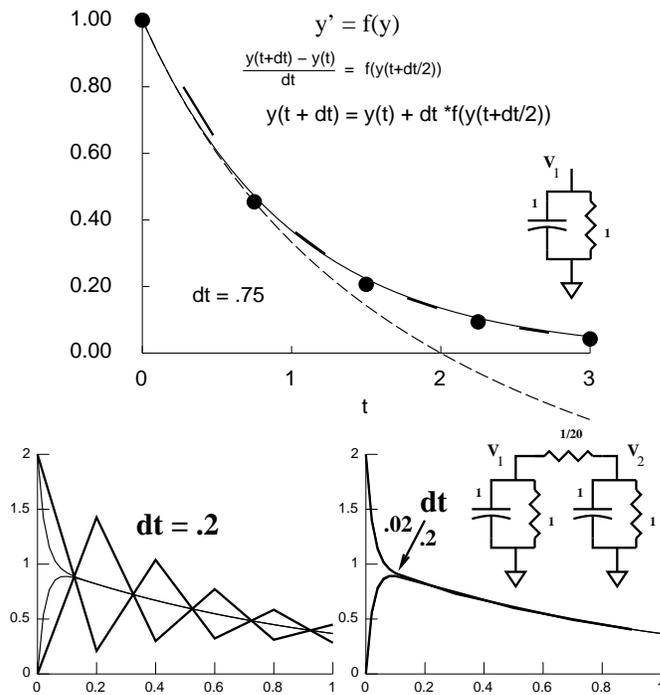
# Forward Euler

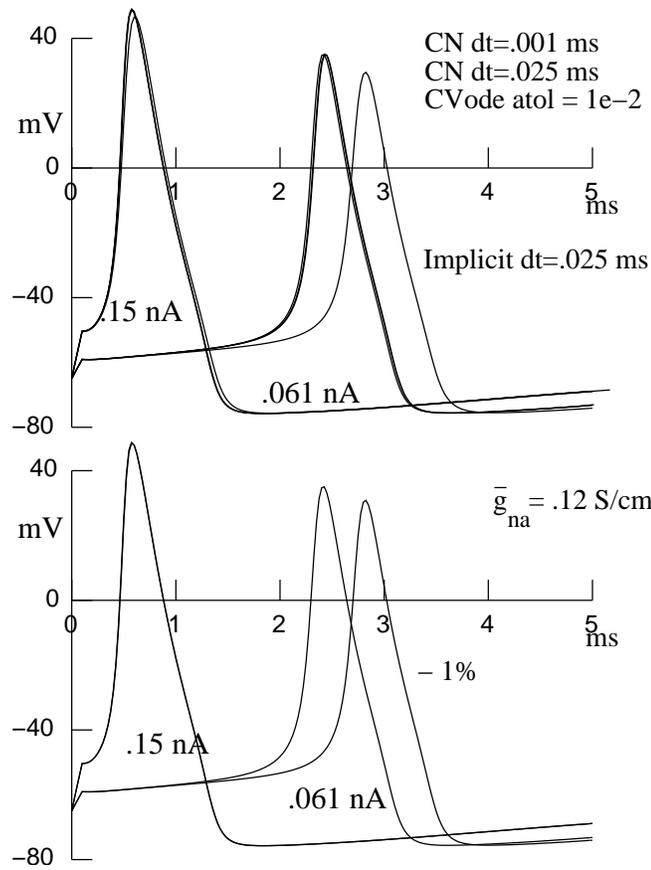


# Backward Euler



### Crank–Nicholson







## Networks: spike-triggered synaptic transmission, events, and artificial spiking cells

1. Define the types of cells
2. Create each cell in the network
3. Connect the cells

## Communication between cells

Gap junctions

Synaptic transmission

graded

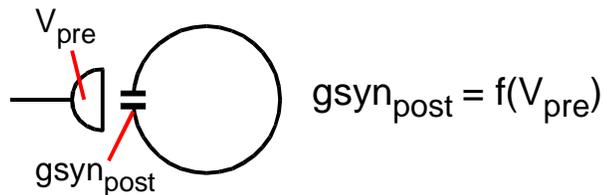
spike-triggered

## Graded synaptic transmission

Physical system:

A presynaptic variable governs  
continuous transmitter release

Transmitter modulates  
a postsynaptic property



Problem: how does postsynaptic cell know  $V_{pre}$ ?

## Graded synaptic transmission *continued*

POINTER links postsynaptic variable  
to presynaptic variable

```
NEURON {
    POINT_PROCESS Syn
    POINTER v_pre
}
```

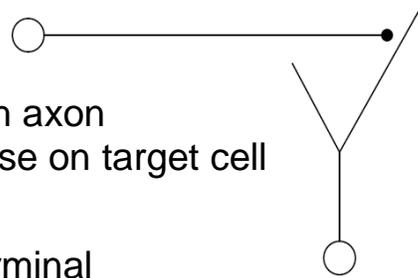
hoc usage

```
objref syn
dend syn = new Syn(0.5)
setpointer syn.v_pre, precell.axon.v(1)
```

## Spike-triggered synaptic transmission

Physical system:

Presynaptic neuron with axon that projects to synapse on target cell



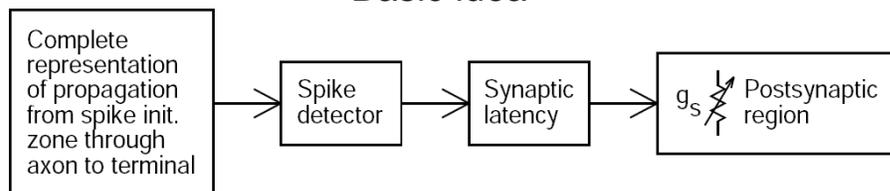
Conceptual model:

Spike in presynaptic terminal triggers transmitter release; presynaptic details unimportant

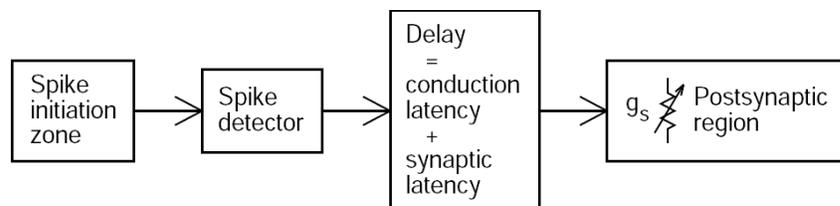
Postsynaptic effect described by DE or kinetic scheme that is perturbed by occurrence of a presynaptic spike

## Spike-triggered transmission: computational implementation

Basic idea



More efficient: "virtual spike propagation"



## The NetCon class

### hoc usage

```
netcon = new NetCon(source, target)
presection netcon = new NetCon(&v(x), \
    target, threshold, delay, weight)
```

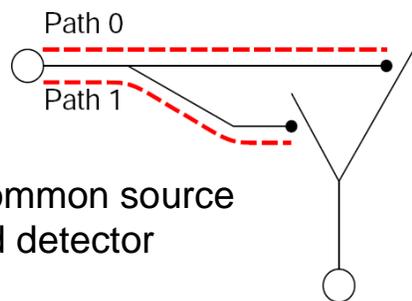
### Defaults

```
threshold = 10
delay = 1 // must be > 0
weight = 0
```

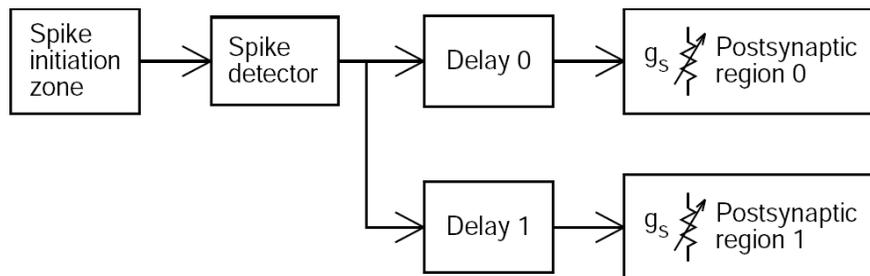
### NMODL specification of synaptic mechanism

```
NET_RECEIVE(weight(microsiemens)) {
    . . .
}
```

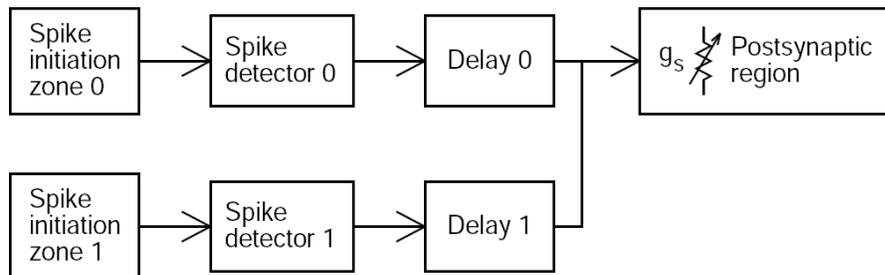
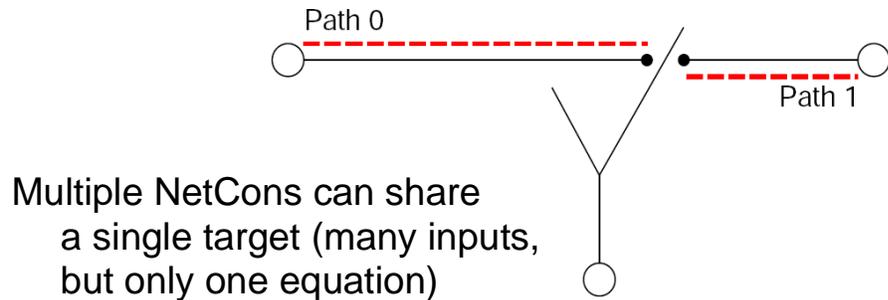
## Efficient divergence



Multiple NetCons with a common source  
share a single threshold detector



## Efficient convergence



## Example: $g_s$ with fast rise and exponential decay

```

NEURON {
  POINT_PROCESS ExpSyn
  RANGE tau, e, i
  NONSPECIFIC_CURRENT i
}

. . . declarations . . .

INITIAL { g = 0 }

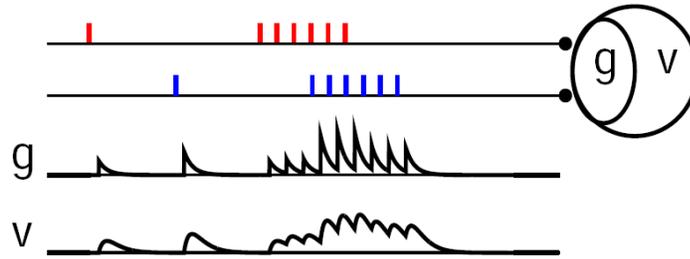
BREAKPOINT {
  SOLVE state METHOD cnexp
  i = g*(v-e)
}

DERIVATIVE state { g' = -g/tau }

NET_RECEIVE(w (uS)) { g = g + w }

```

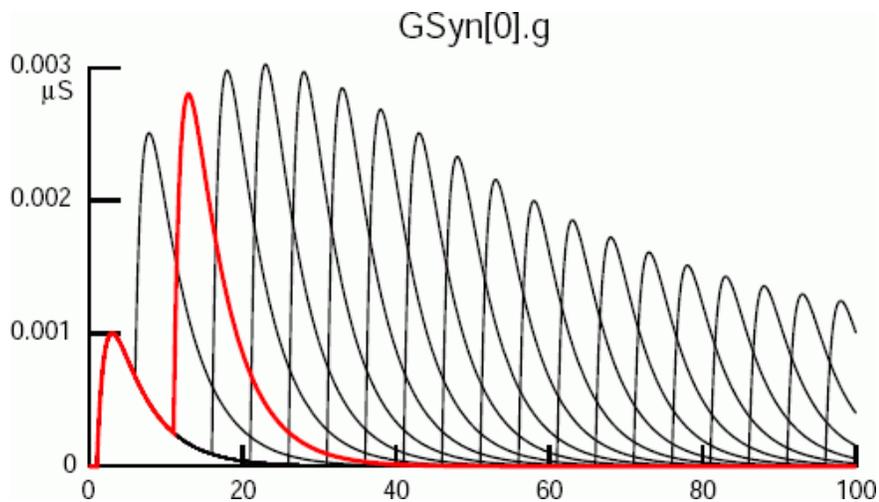
### $g_s$ with fast rise and exponential decay *continued*



```

BREAKPOINT {
  SOLVE state METHOD cnexp
  i = g*(v-e)
}
DERIVATIVE state { g' = -g/tau }
NET_RECEIVE(w (uS)) { g = g + w }
    
```

### Example: use-dependent synaptic plasticity

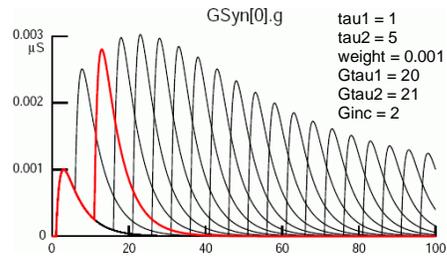


## Use-dependent synaptic plasticity *continued*

```

BREAKPOINT {
  SOLVE state METHOD cnexp
  g = B - A
  i = g*(v-e)
}
DERIVATIVE state {
  A' = -A/taul
  B' = -B/tau2
}
NET_RECEIVE(weight (uS), w, G1, G2, t0 (ms)) {
  INITIAL {w=0 G1=0 G2=0 t0=t}
  G1 = G1*exp(-(t-t0)/Gtau1)
  G2 = G2*exp(-(t-t0)/Gtau2)
  G1 = G1 + Ginc*Gfactor
  G2 = G2 + Ginc*Gfactor
  t0 = t
  w = weight*(1 + G2 - G1)
  g = g + w
  A = A + w*factor
  B = B + w*factor
}

```



## Artificial spiking cells

### "Integrate and fire" cells

Prerequisite: all state variables must be  
analytically computable from a new initial condition

Orders of magnitude faster than numerical integration

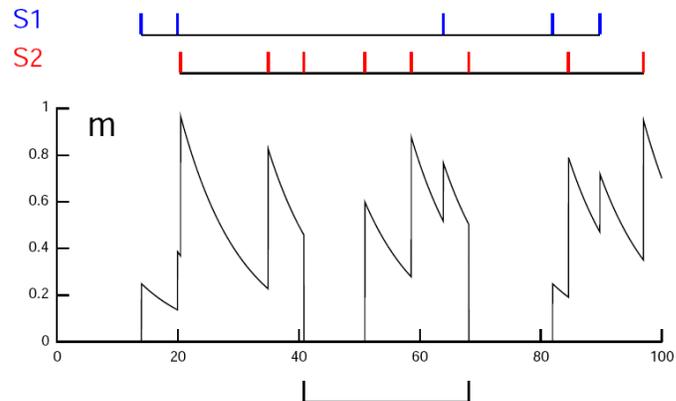
Event-driven simulation run time is

*proportional* to # of received events

*independent* of # of cells, # of connections,  
and problem time

Hybrid networks

## Example: leaky integrate and fire model

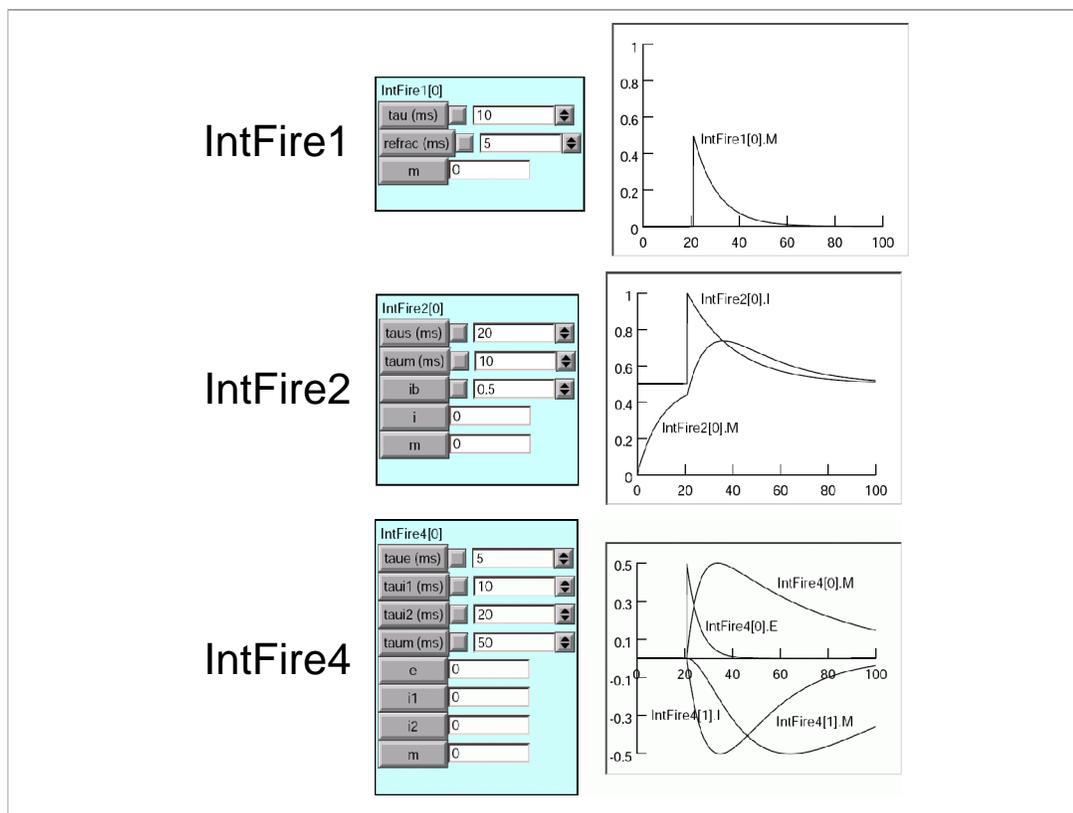


## Leaky integrate and fire model *continued*

```

NEURON {
  ARTIFICIAL_CELL IntFire
  RANGE tau, m
}
. . . declarations . . .
INITIAL { m = 0    t0 = t }
NET_RECEIVE (w) {
  m = m*exp(-(t-t0)/tau)
  t0 = t
  m = m + w
  if (m > 1) {
    net_event(t)
    m = 0
  }
}

```



## Defining the types of cells

### Artificial spiking cells

ARTIFICIAL\_CELL with a NET\_RECEIVE block  
 that calls net\_event

NetStim, IntFire1, IntFire2, IntFire4

### Biophysical model cells

"Real" model cells

Sections and density mechanisms

Synapses are POINT\_PROCESSes  
 that affect membrane current  
 and have a NET\_RECEIVE block,  
 e.g. ExpSyn, Exp2Syn

## Defining types of biophysical model cells

### Encapsulate in a class

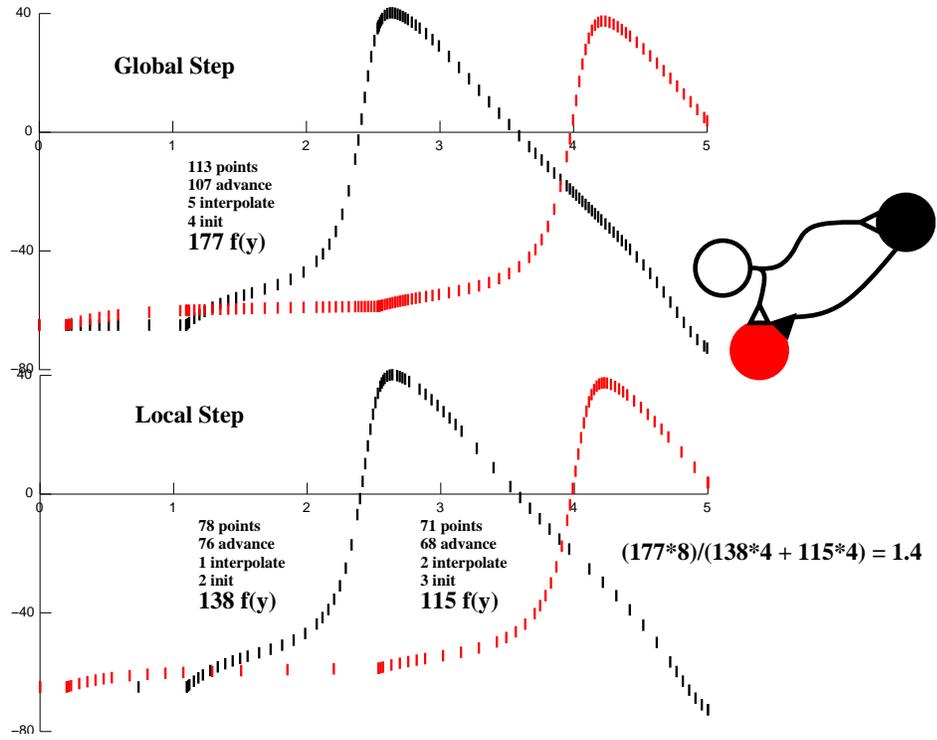
```
begintemplate Cell
  public soma, E, I
  create soma
  objref E, I
  proc init() {
    soma {
      insert hh
      E = new ExpSyn(0.5)
      I = new Exp2Syn(0.5)
      I.e = -80
    }
  }
endtemplate Cell

objref bag_of_cells
bag_of_cells = new List()
for i = 1,1000 bag_of_cells.append(new Cell())
```

## Connecting cells

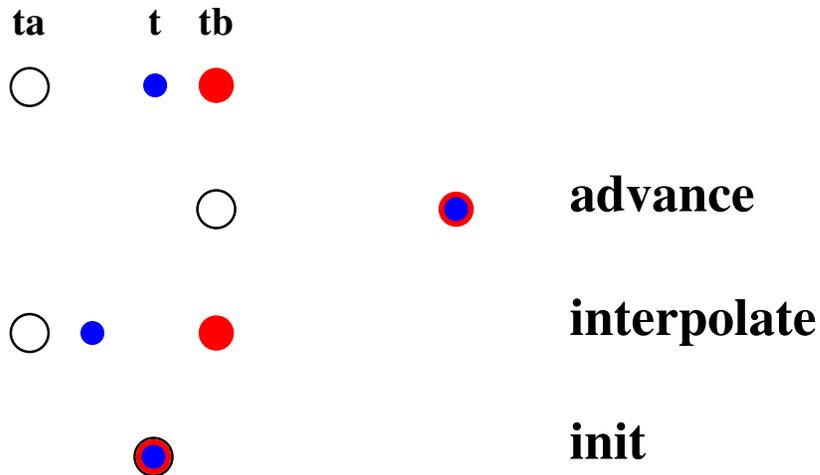
Hint: outer loop should iterate over targets

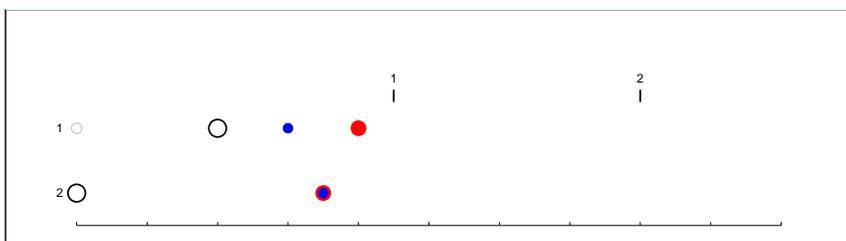
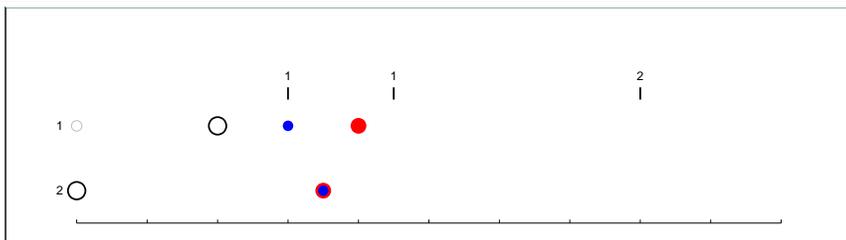
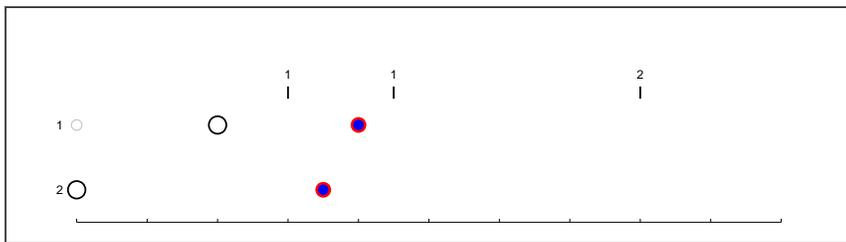
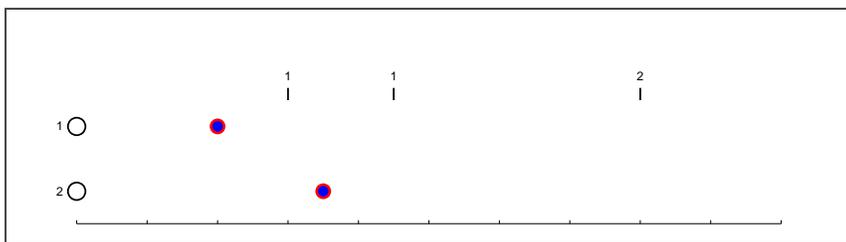
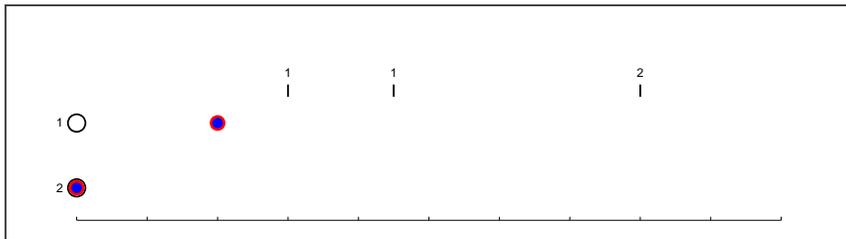
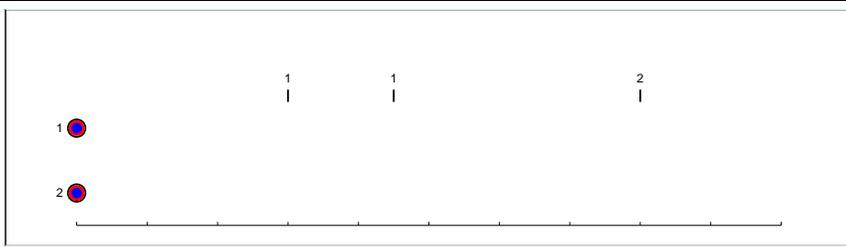
```
for each target cell {
  for each source that projects to this target cell {
    set up a NetCon that connects source to target
  }
}
```

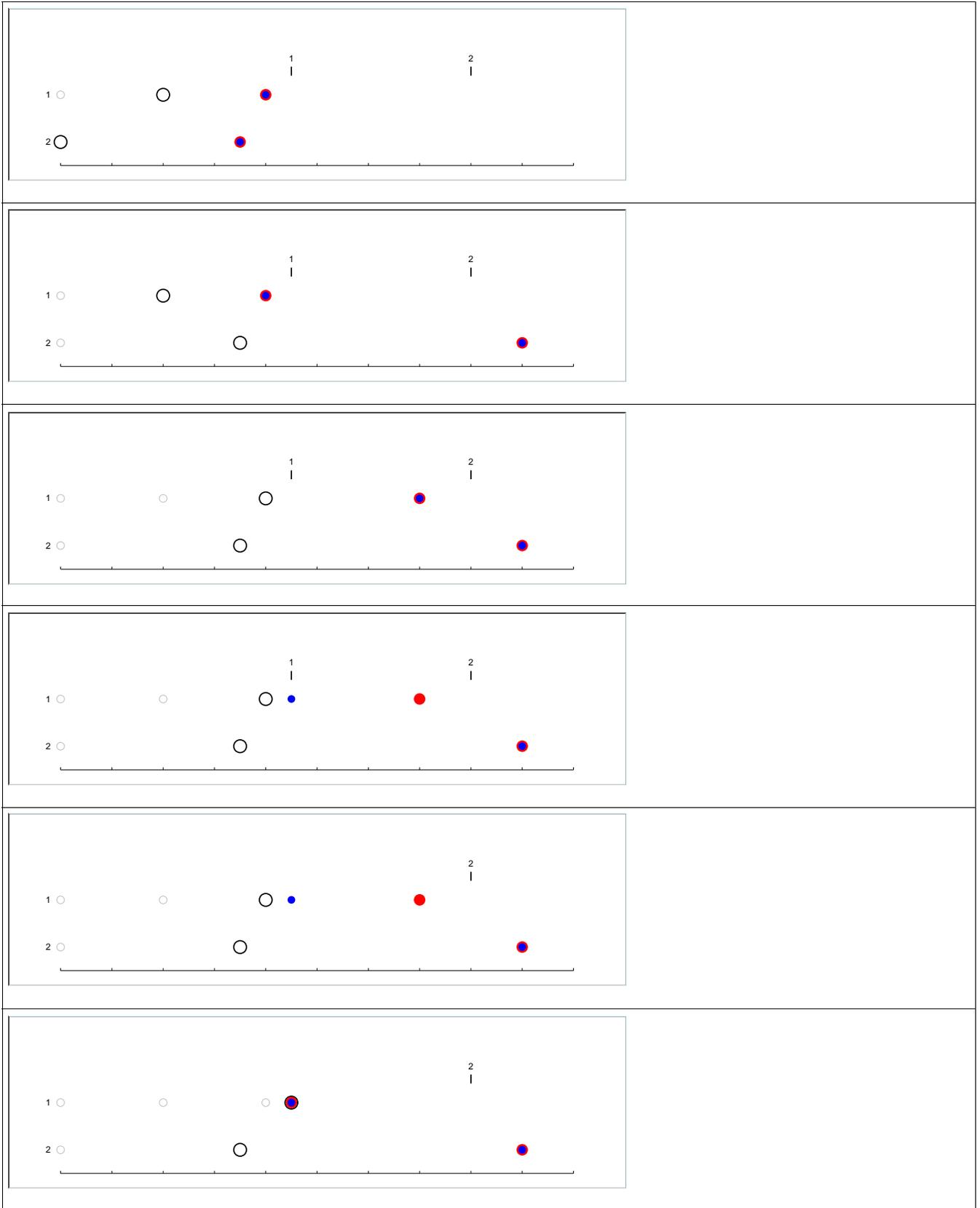


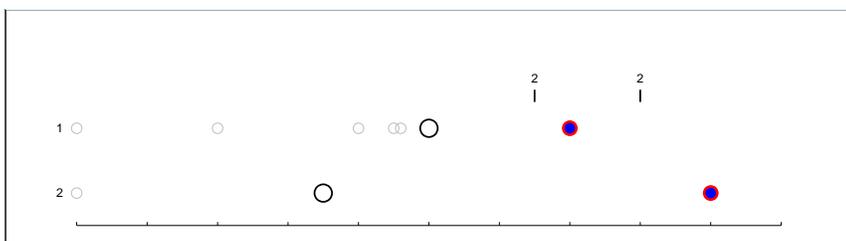
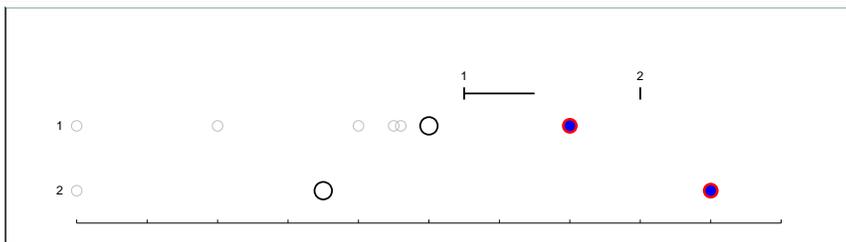
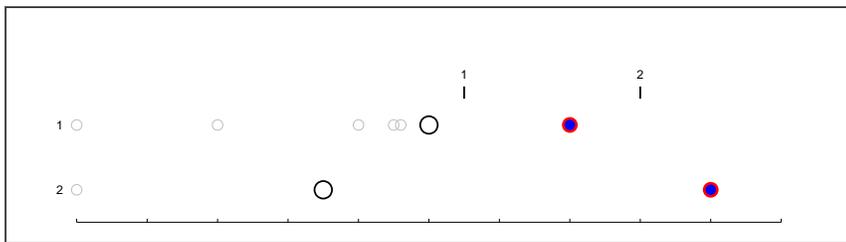
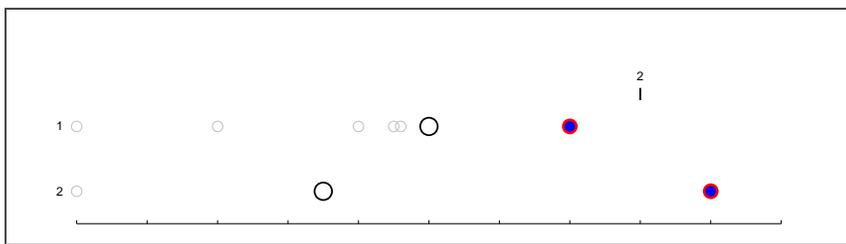
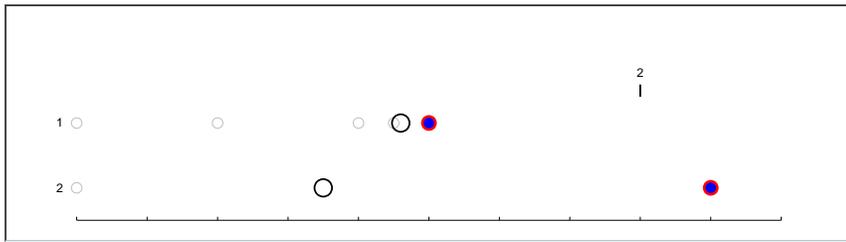
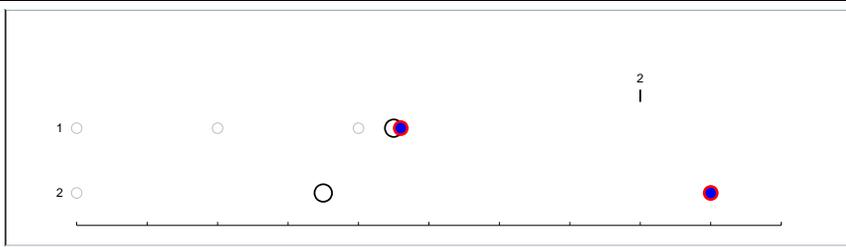
**One integrator instance per cell**

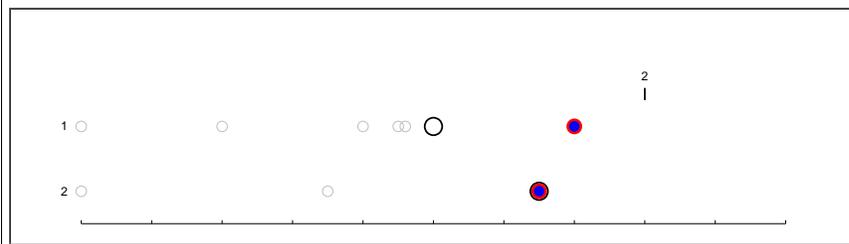
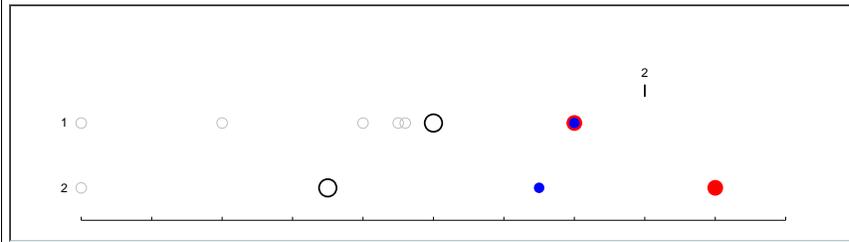
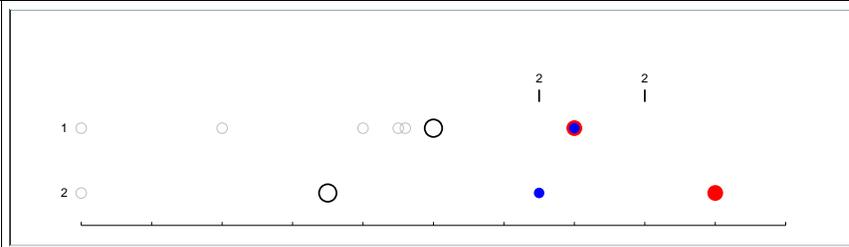
$$\forall i, j: ta_i \leq tb_j$$













## Parallel Computation

"Faster" is the only reason

But...

greater programming complexity  
new kinds of bugs  
...and not much help for fixing them.

Can the day or week of user effort be recovered?

8192 processor EPFL IBM BlueGene  
1 hour at 700MHz  
3 months at 3GHz

## Parallel Computation

A simulation run takes about a second

want to do 1000's of them,  
varying a dozen or so parameters.

- Screensaver Calin-Jageman and Katz, 2006
- Bulletin-board (Linda)

A simulation run takes hours.

want to spread the problem over several machines.

## Parallel Computation

A simulation run takes hours.

want to spread the problem over several machines.

Network

Subnets on different machines

Cells communicate by:

logical spike events with significant  
axonal, synaptic delay.

postsynaptic conductance depends  
continuously on presynaptic voltage.

gap junctions

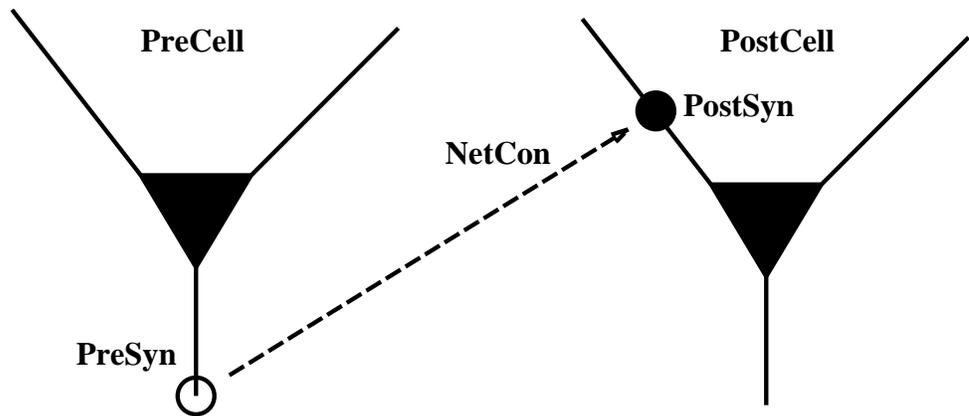
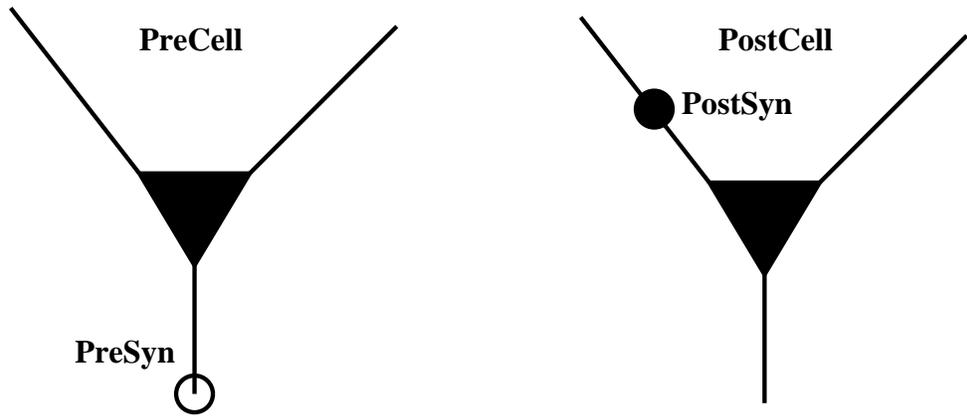
## Parallel Computation

A simulation run takes hours.

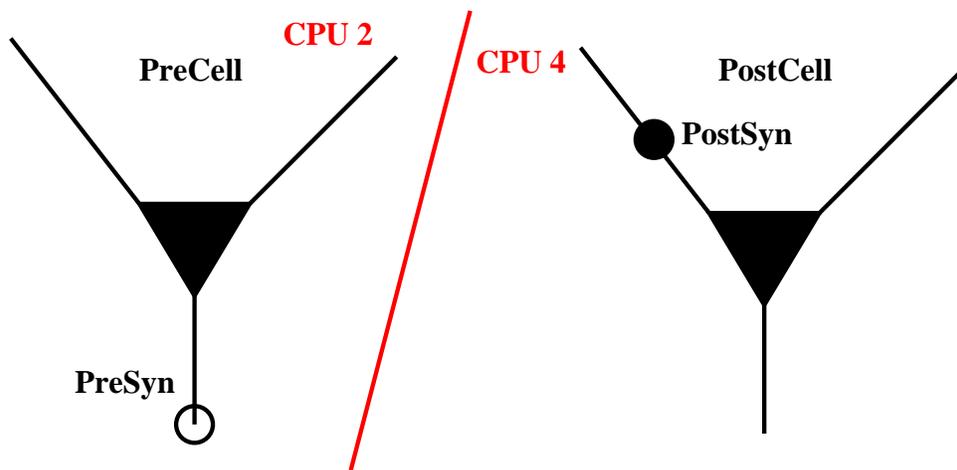
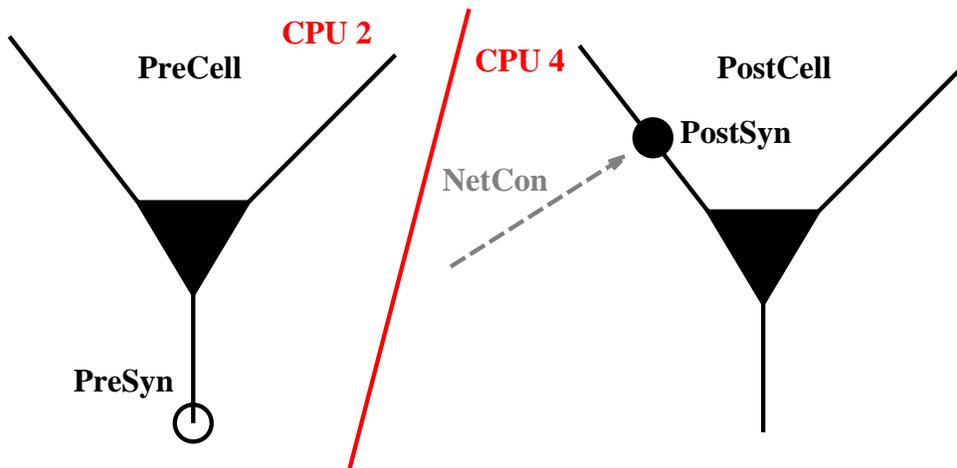
want to spread the problem over several machines.

Single cells

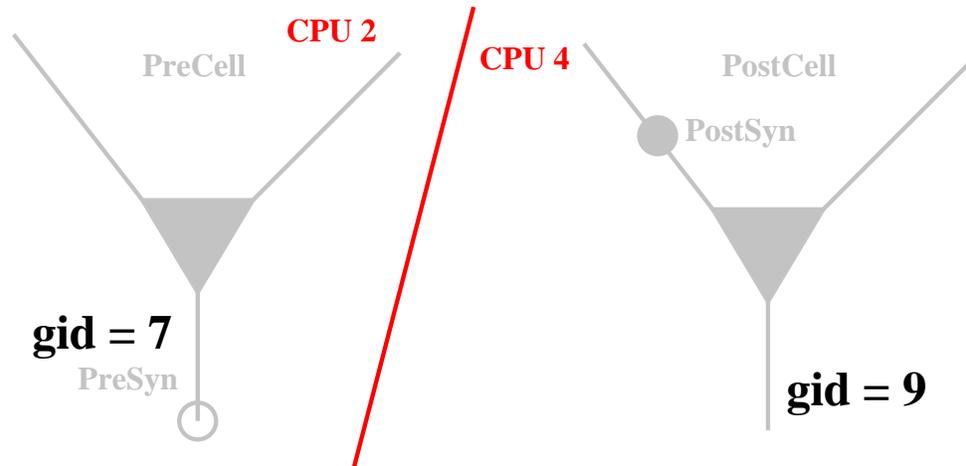
portions of the tree cable equation on  
different machines.



```
nc = new NetCon(PreSyn, PostSyn)
```



```
pc = new ParallelContext()
```



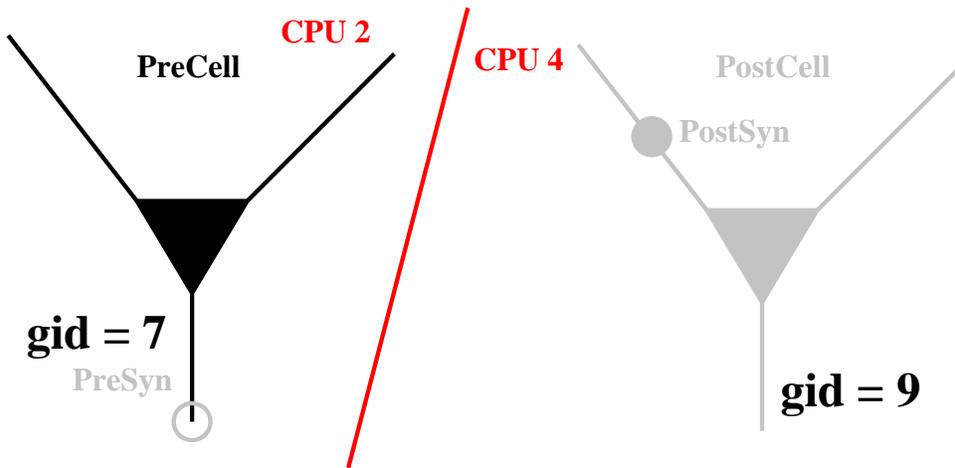
**Every spike source (cell) must have a global id number.**

<b>CPU 0</b>		<b>CPU 3</b>	<b>CPU 4</b>
pc.id 0		pc.id 3	pc.id 4
pc.nhost 5		pc.nhost 5	pc.nhost 5
ncell 14	...	ncell 14	ncell 14
gid		gid	gid
0		3	4
5		8	9
10		13	

**An efficient way to distribute:**

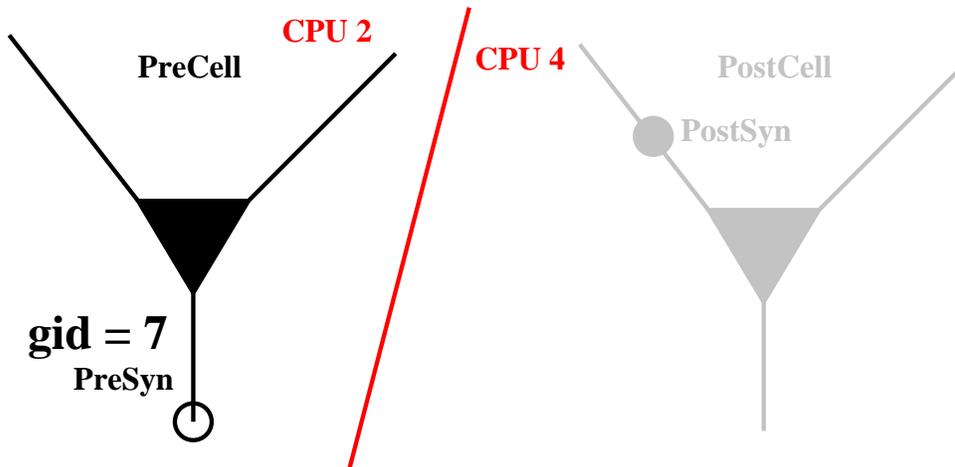
```
for (gid = pc.id; gid < ncell; gid += pc.nhost)
    pc.set_gid2node(gid, pc.id)
    ...
}
```

**body executed only ncell/nhost times, not ncell.**



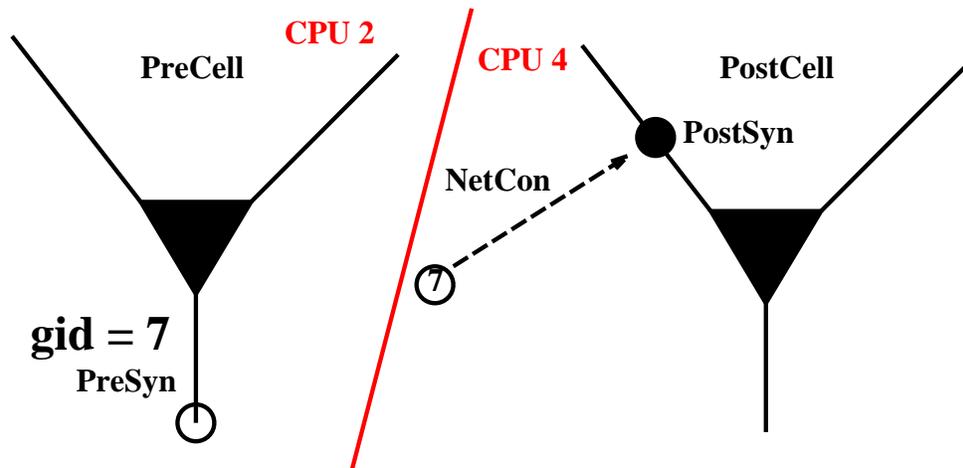
**Create cell only where the gid exists.**

```
if (pc.gid_exists(7)) {  
    PreCell = new Cell()  
}
```



**Associate gid with spike source.**

```
nc = new NetCon(PreSyn, nil)  
pc.cell(7, nc)
```



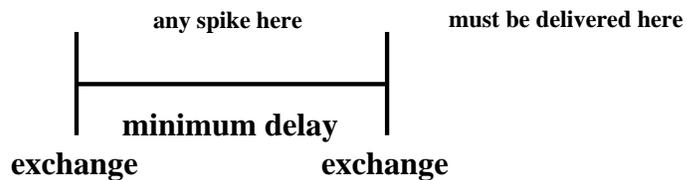
**Create NetCon on CPU where target exists.**

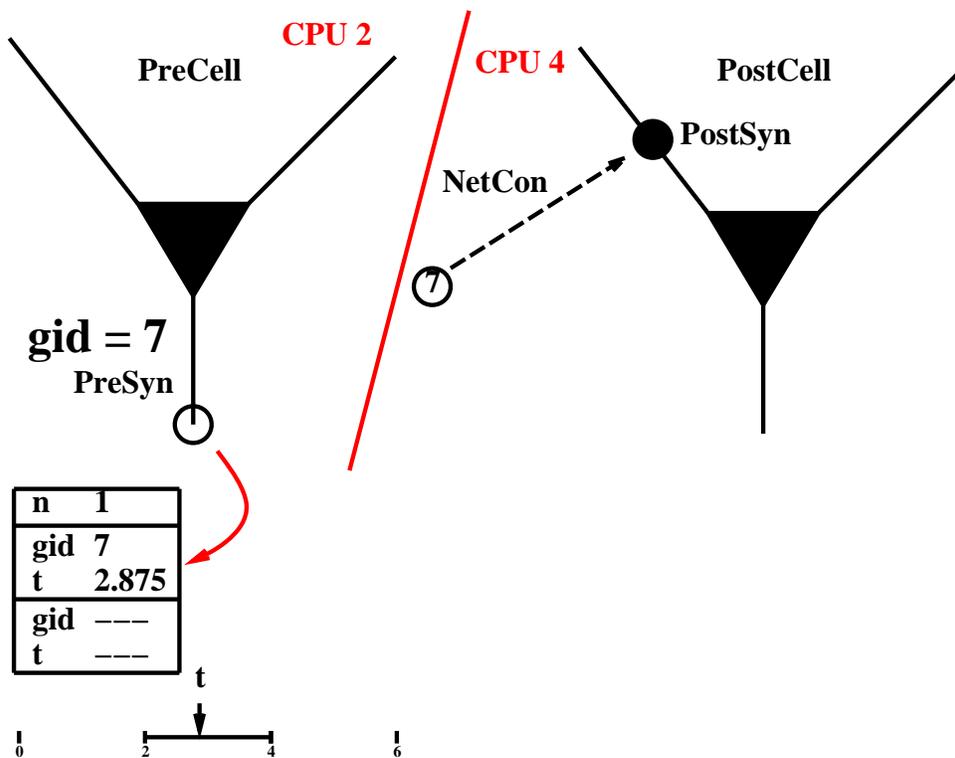
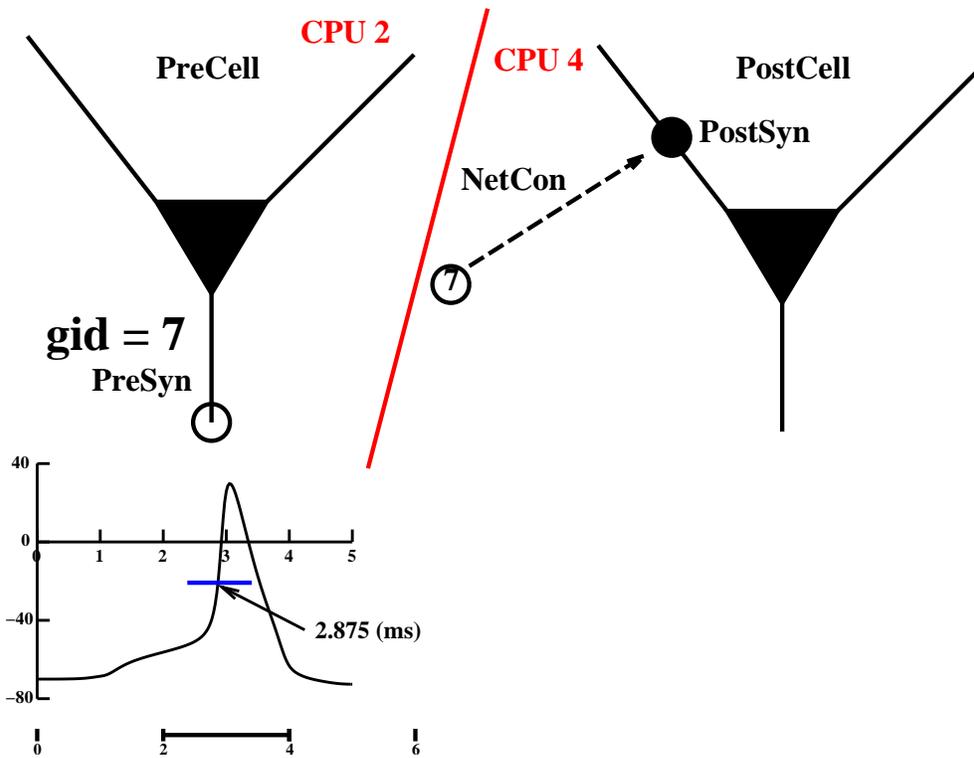
```
nc = pc.gid_connect(7, PostSyn
```

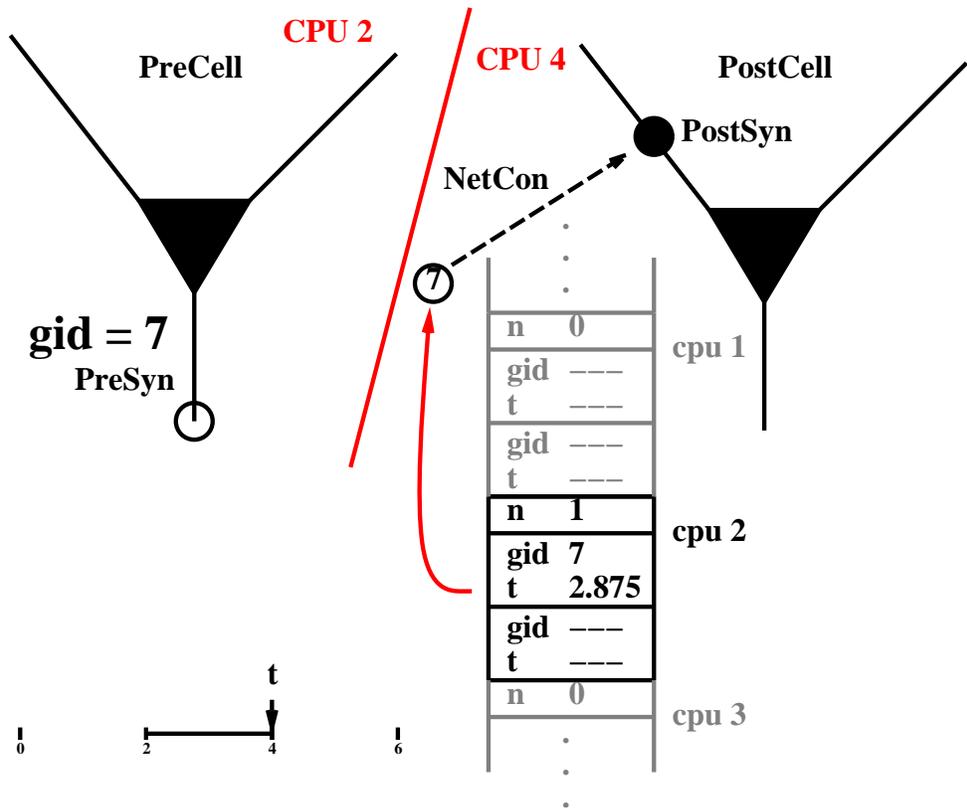
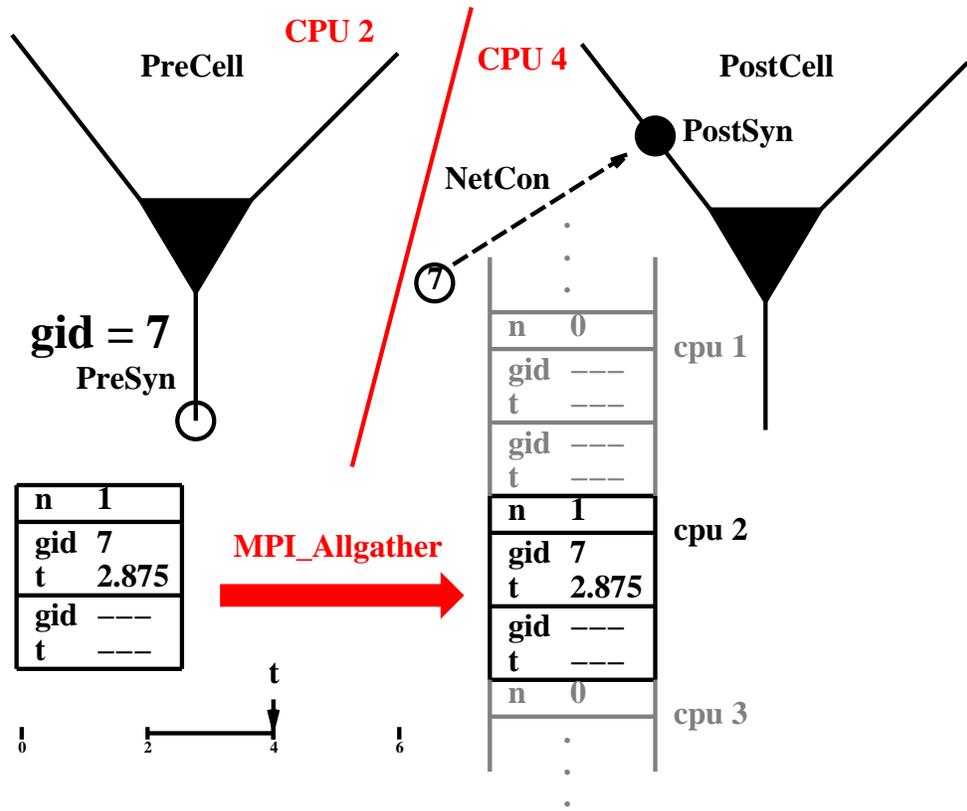
## Run using the idiom

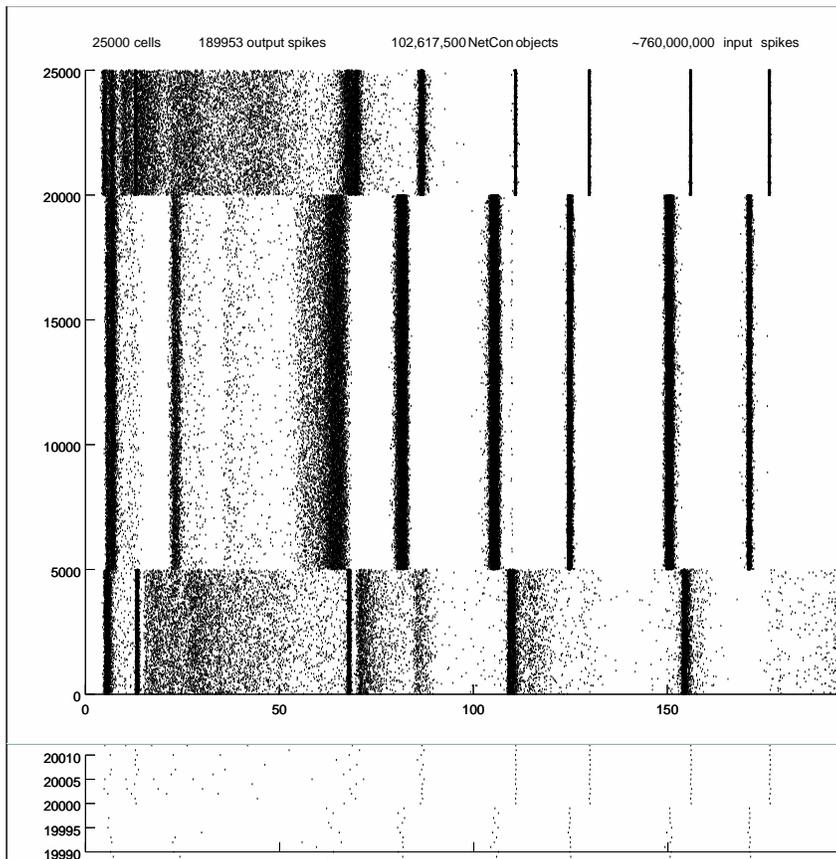
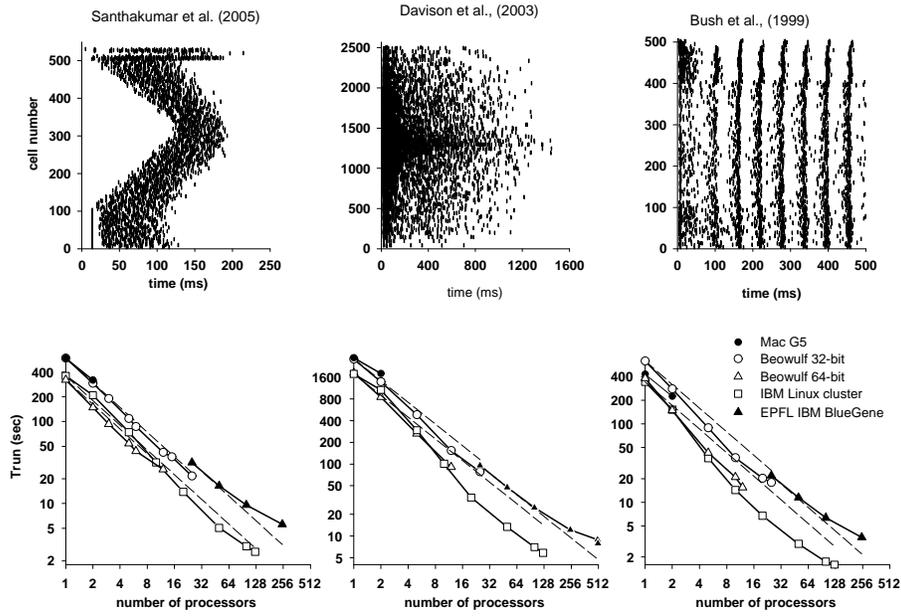
```
pc.set_maxstep(10)
stdinit()
pc.solve(tstop)
```

`pc.set_maxstep()` uses  
**MPI\_Allreduce**  
 to determine minimum delay.









# More Efficient Spike Management

## Spike exchange buffer compression (Requires fixed step method)

Reduce integration interval to < 256 dt steps, code the double spiketime as a byte.

If there are < 256 cells on each CPU code the int gid as a char local\_id.

Select reasonable MPI\_Allgather buffer size to send n spikes before requiring an MPI\_Allgather overflow message.

## Bin Queue (Requires fixed step method)

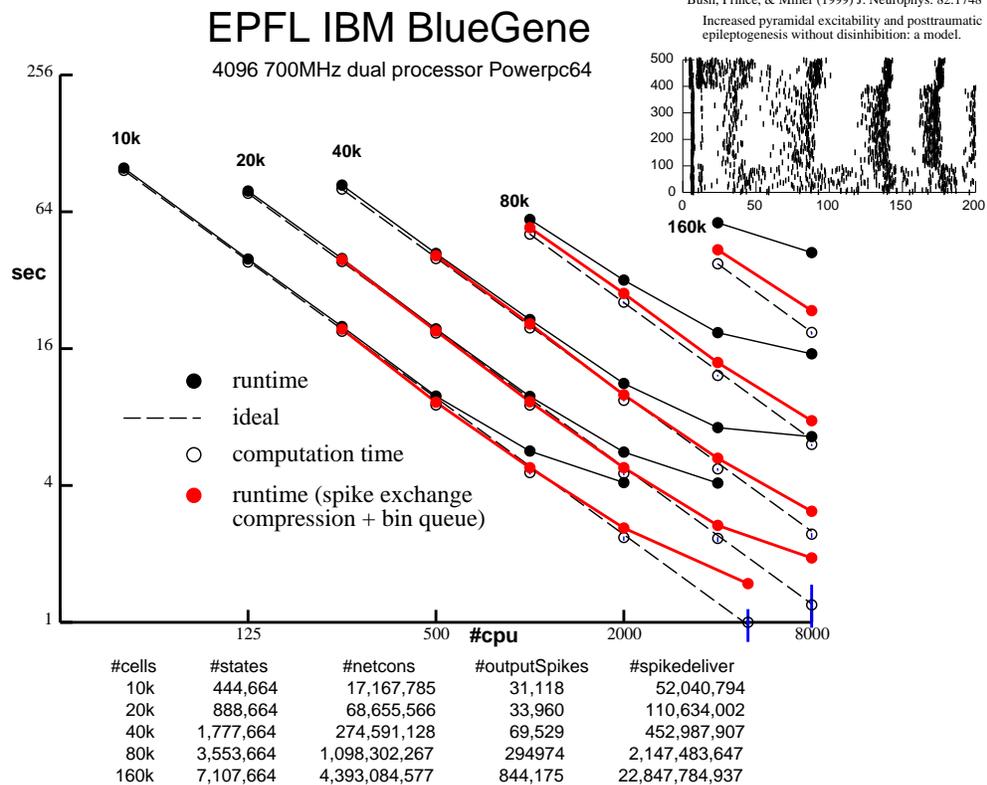
need at least maximum NetCon delay / dt bins

## ARTIFICIAL\_CELL SelfEvents bypass queue

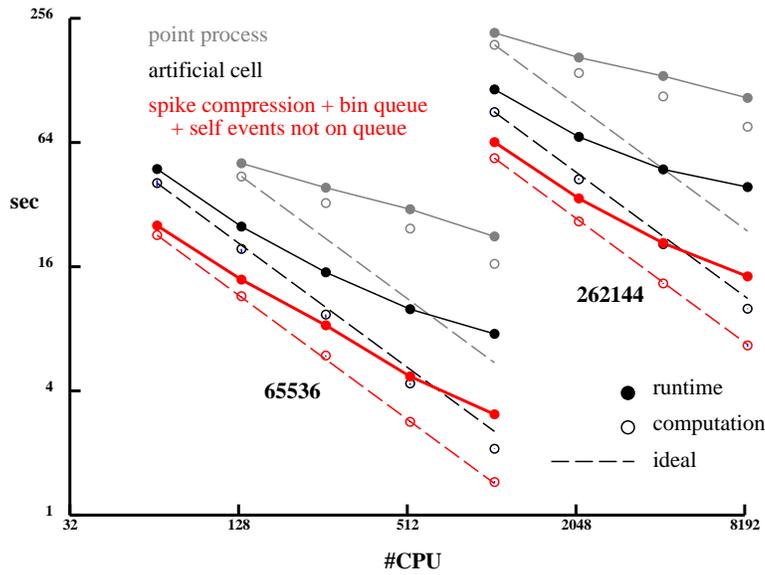
(Requires the integration interval be <= the positive global minimum NetCon delay)

On every incoming NetCon event check to see if SelfEvent < t

After each integration interval iterate over outstanding SelfEvents to deliver all that are < t.



## Artificial Spiking Net Performance

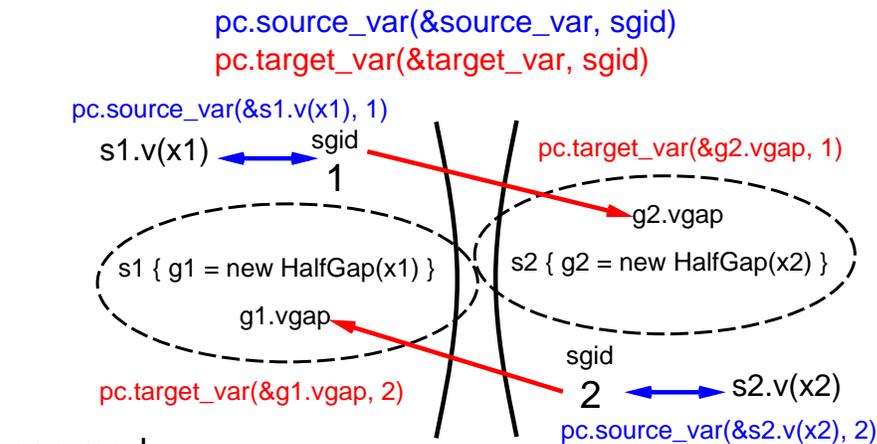


Each cell fires randomly every 10 to 20 ms.  
 65K cells, 1000 random connections per cell  
 256K cells, 10,000 random connections per cell

tstop = 200(ms)  
 delay = 1(ms)  
 weight = 0

## Gap Junction Specification

### Continuous Voltage Exchange

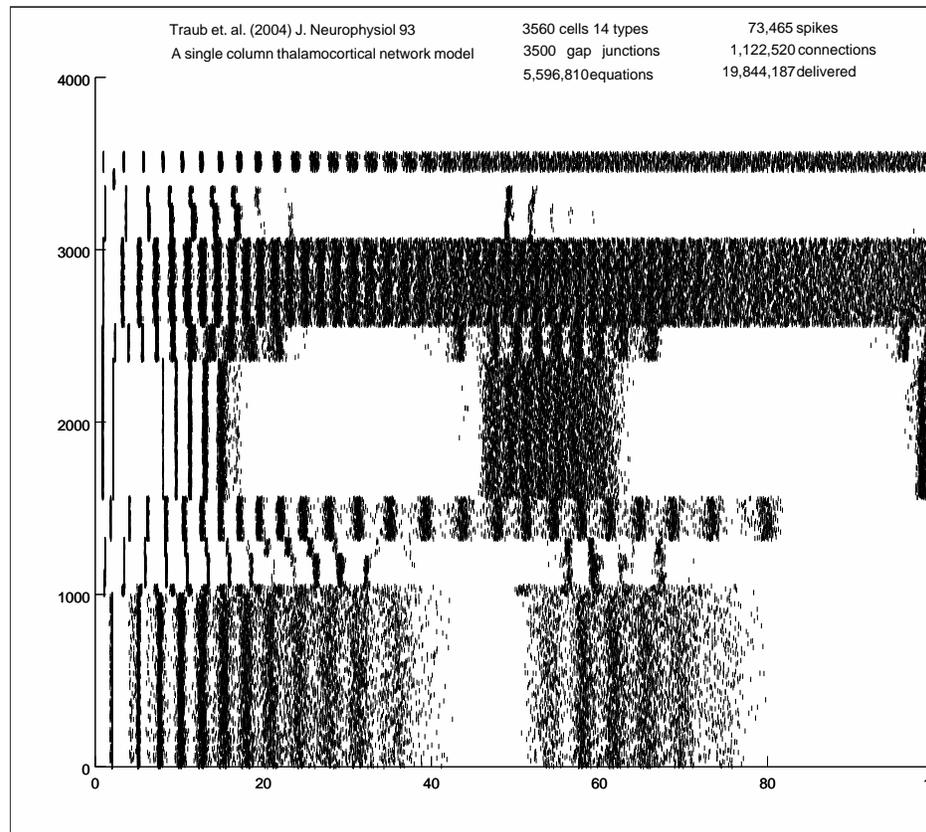


#### gap.mod

```

NEURON {
    POINT_PROCESS HalfGap
    ELECTRODE_CURRENT i
    RANGE r, i, vgap
}
PARAMETER { r = 1e9 (megohm) }

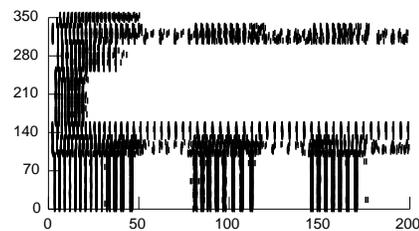
ASSIGNED {
    v (millivolt)
    vgap (millivolt)
    i (nanoamp)
}
BREAKPOINT { i = (vgap - v)/r }
    
```



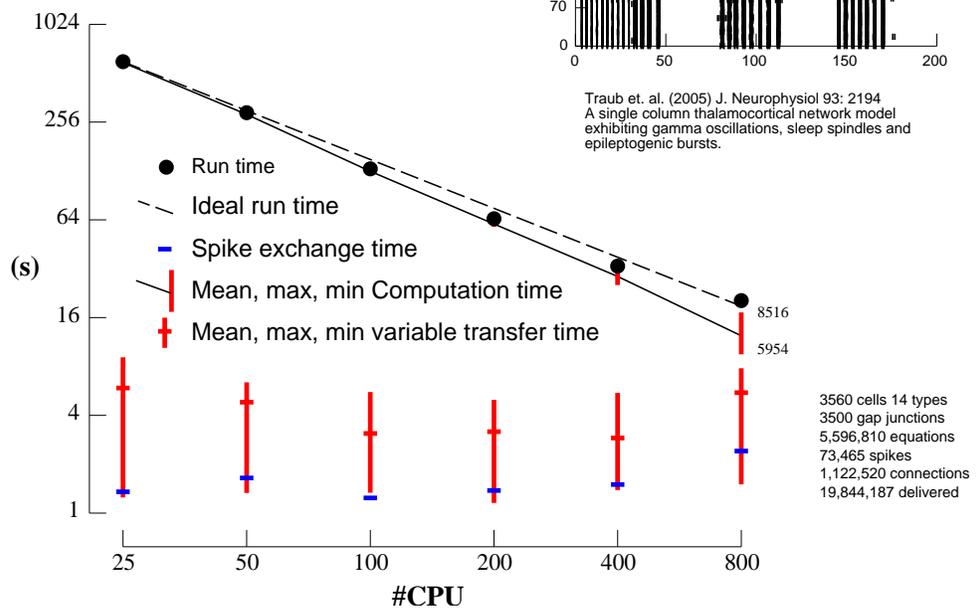
Pittsburgh Supercomputing Center

Bigben Cray XT3

2068 2.4 GHz Opteron Processors

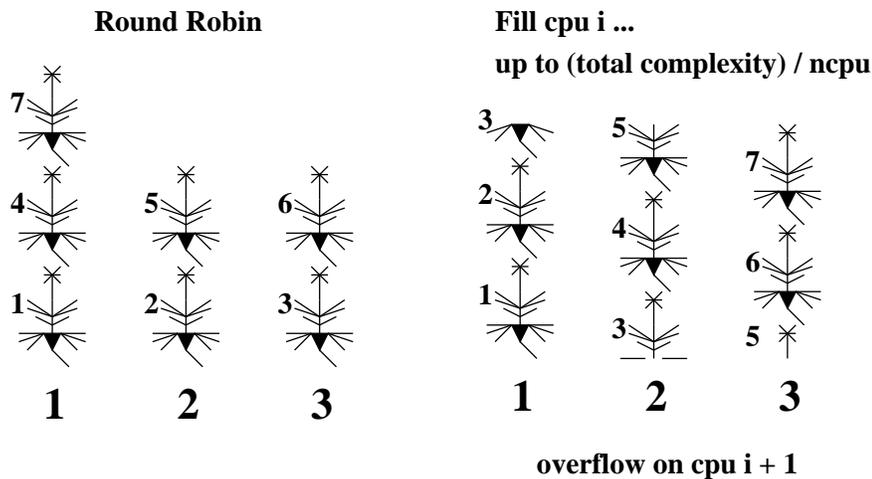


Traub et al. (2005) J. Neurophysiol 93: 2194  
A single column thalamocortical network model exhibiting gamma oscillations, sleep spindles and epileptogenic bursts.

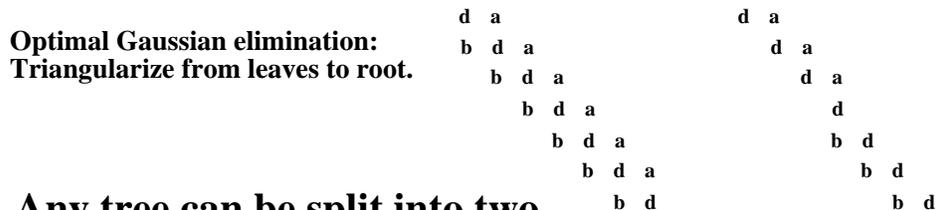


# Load Balance

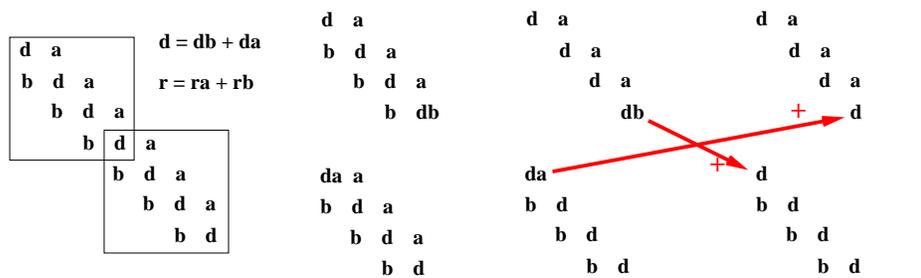
7 cells 3 cpus (or heterogeneous cells)



but... what is the overhead of splitting a cell?



Any tree can be split into two subtrees with a shared root node.



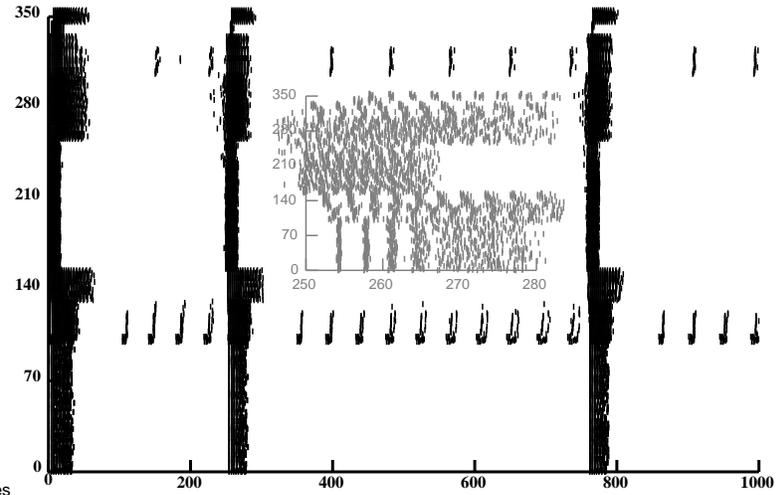
No change in Stability  
Accuracy  
Complexity

Also exchange ra and rb.

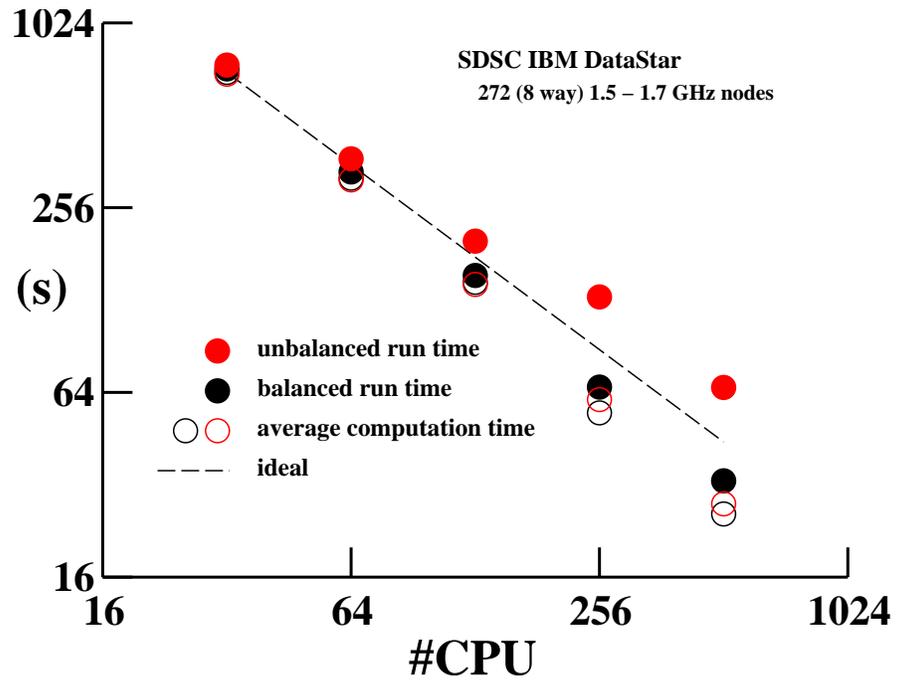
356 cells equations  
559,808

### 1/10 size Traub model

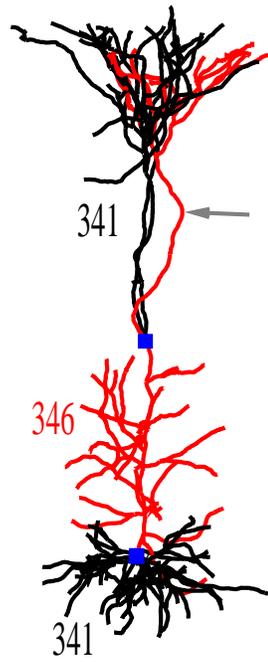
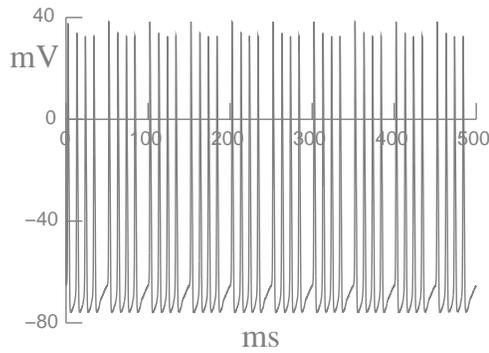
10 nRT (2306)  
10 TCR (5237)  
10 deepLTS (2306)  
10 deeppax (2306)  
10 deepbask (2306)  
50 nontuftRS (1789)  
  
20 tuftRS (2304)  
80 tuftIB (2304)  
  
24 spinstell (2140)  
9 supLTS (2306)  
9 supaxax (2306)  
9 supbask (2306)  
5 supplyFRB (2926)  
  
100 supplyRS (2926)  
  
885,312 total  
1,298,688 with synapses



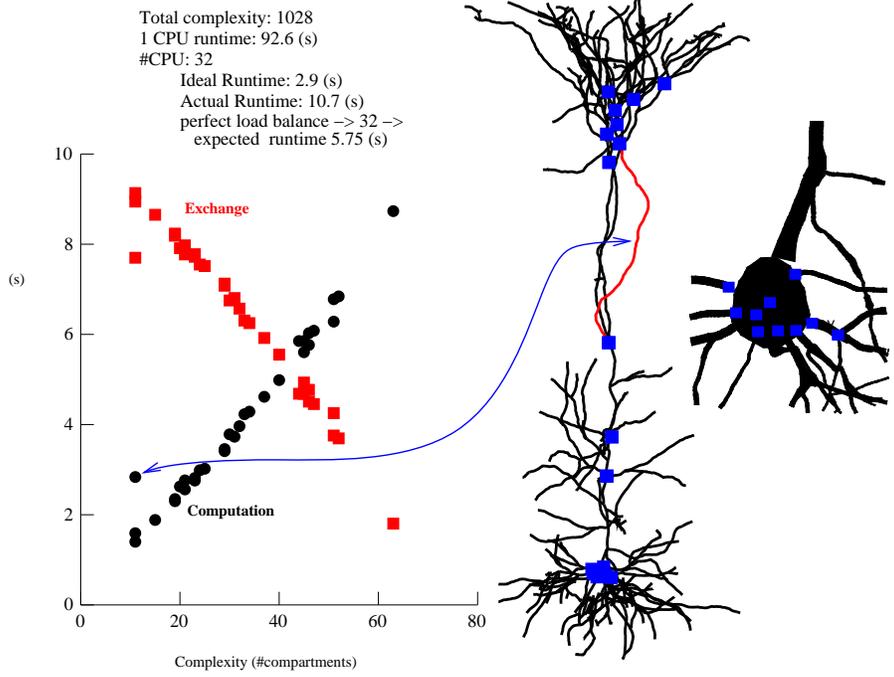
ncpu	avgload	round robin maxload	metis	split cell maxload
32	40584	42870 6%	1%	40963 0%
64	20292	23310 15%	5%	20496 1%
128	10146	13350 32%	18%	10260 1%
256	5073	9461 86%	57%	5237 3%
512	2536	5475 116%	116%	2839 11%



#CPU	Runtime (s)
1	19.1
3	6.5



```
rank section x sid exact
0 dend[113] pc.multisplit( 0, 0, 1)
1 apic[67] pc.multisplit( 0, 1, 1)
2 soma pc.multisplit(.5, 0, 1)
2 apic[65] pc.multisplit( 1, 1, 1)
```



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Pittsburgh Supercomputer Center for the use of the Cray XT3.

